## Computational Cognitive Science



Lecture 19: HMMs and more complex grammars

## Last time

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- Grammars that incorporate parts of speech can be useful for greatly minimising the size of the grammar required
- Hidden Markov models, which involve hidden states that generate observations, can capture parts of speech
- We can use such models to generate sequences of observations in both linguistic and non-linguistic contexts


## Plan

- Last time: introduction to HMMs
- Limitations of n-grams applied to language
- Basics of HMMs
- Today: finishing HMMs, and more complex structures
- Determining the likelihood of a given observation
- Calculating the most likely state sequence
- Finding the best HMM for given data
- More complex models of language


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## Three fundamental questions for HMMs

- Given a model $M=(A, B, \Pi)$, how do we efficiently compute how likely a certain observation is?
- Given a sequence of observations $Y$ and a model $M$, how do we infer the state sequence that best explains the observations?
- Given an observation sequence Y and a space of possible models found by varying the model parameters $M=$ ( $A, B, \Pi$ ), how do we find the model that best explains the observed data?

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[^1]
## Computing likelihood of observations

For any output sequence $Y=\left(y_{1}, \ldots, y_{T}\right)$ we can calculate the probability of observing it by summing over all possible sequences of hidden states that could have generated it:

$$
p(Y)=\sum_{X} p(Y \mid X) p(X)
$$

Example: simple language
How likely are you to see "he eats"?

(0.5) verb $\rightarrow$ eats
$(0.5)$ verb $\rightarrow$ runs
$(0.3)$ pro $\rightarrow$ he
$(0.3)$ pro $\rightarrow$ she
(0.4) pro $\rightarrow$ it
$(0.7)$ det $\rightarrow$ the
(0.3) det $\rightarrow$ a
$(0.4)$ noun $\rightarrow$ boy
$(0.4)$ noun $\rightarrow$ dog
(0.2) noun $\rightarrow$ tiger
(1.0) adj $\rightarrow$ happy
$P($ he eats $\mid A, B, \Pi)$

$$
\begin{aligned}
& \quad=\mathrm{P}(\text { pro } \mid \mathrm{S}) \mathrm{P}(\text { he } \mid \text { pro }) \mathrm{P}(\text { verb } \mid \text { pro }) \mathrm{P}(\text { eats } \mid \text { verb }) \mathrm{P}(\mathrm{E} \mid \text { verb }) \\
& =0.7 * 0.3 * 1.0 * 0.5 * 1.0 \\
& =0.105
\end{aligned}
$$

But that was easy, because there was just one way to generate that observation

## Example: Mitee the warrior

 How likely are you to see "zzz snort"?State transition matrix $A$ :

|  | Asleep | Calm | Angry | Hungry |
| :--- | :--- | :--- | :--- | :--- |
| Asleep | 0.5 | 0.2 | 0.1 | 0.2 |
| Calm | 0.4 | 0.3 | 0.1 | 0.2 |
| Angry | 0.1 | 0.2 | 0.6 | 0.1 |
| Hungry | 0.1 | 0.1 | 0.5 | 0.3 |

Initial state probabilities $\Pi$ :

| Asleep | Calm | Angry | Hungry |
| :--- | :--- | :--- | :--- |
| 0.3 | 0.3 | 0.2 | 0.2 |

Output symbol matrix $B$ :

|  | Roar | Zzz | Snort | Grumble |
| :--- | :--- | :--- | :--- | :--- |
| Asleep | 0.0 | 0.9 | 0.1 | 0.0 |
| Calm | 0.0 | 0.0 | 0.8 | 0.2 |
| Angry | 1.0 | 0.0 | 0.0 | 0.0 |
| Hungry | 0.2 | 0.0 | 0.0 | 0.8 |

$P($ zzz snort $\mid A, B, \Pi)$

$$
\begin{aligned}
= & P(\text { zzz } \mid \text { asleep }) P(\text { asleep }) P(\text { calm } \mid \text { asleep }) P(\text { snort } \mid \text { calm })+ \\
& P(\text { zzz } \mid \text { asleep }) P(\text { asleep }) P(\text { asleep } \mid \text { asleep }) P(\text { snort } \mid \text { asleep }) \\
= & (0.9)(0.3)(0.2)(0.8)+(0.9)(0.3)(0.5)(0.1) \\
= & 0.0675+0.0135 \\
= & 0.081
\end{aligned}
$$

## Computing likelihood of observations

You can see that this will grow increasingly difficult as the HMM grows increasingly larger (or there are fewer zeros in the transition matrix)

$$
p(Y)=\sum_{X} p(Y \mid X) p(X)
$$

Having to sum over every possible set of hidden states, in general, requires on the order of $N^{T+1}$ multiplications, where $T=\#$ of time steps, and $N=$ the number of states. The complexity is thus $O\left(N^{T}\right)$

## Simplifying the computation

Luckily, in order to calculate the most likely path we don't have to sum over all possible state sequences


Because of the limited horizon property, the probability of the path at any one point only depends on the probability of the current point and the probability of the previous point

## Forward algorithm

An algorithm for efficiently calculating the probability of a sequence of observations

Incremental: at each observation step, you find the most likely path until that point

Complexity is $\mathrm{O}\left(\mathrm{N}^{2} \mathrm{~T}\right)$, assuming a fully connected model - a big improvement over $\mathrm{O}\left(\mathrm{N}^{\top}\right)$

Example: Mitee the warrior How likely are you to see
"zzz snort grumble roar"?
State transition matrix $A$ :

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Initial state probabilities $\Pi$ :

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grumble roar

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There is only
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Output symbol matrix $B$ :

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roar

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$(0.0135)(0.2)(0.2)+$

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$(0.0135)(0.2)(0.2)+(0.0432)(0.2)(0.3)$

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$0.00313 * 0.2 * 0.2+$

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Total probability of observing this sequence:
$0.00067+0.00485=0.055$


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ZZZ

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grumble roar

This is called the forward algorithm, because we calculated incrementally moving forward in time

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- Given a model $M=(A, B, \Pi)$, how do we efficiently compute how likely a certain observation is?
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Idea: what if we maximise as we go through the trellis, rather than sum up all of the states?

## Viterbi algorithm

An algorithm for efficiently calculating the most likely path through an HMM, given a sequence of observations

Incremental: at each observation step, you find the most likely path until that point

Complexity is $\mathrm{O}\left(\mathrm{N}^{2} \mathrm{~T}\right)$, assuming a fully connected model - a big improvement over $\mathrm{O}\left(\mathrm{N}^{\top}\right)$

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Example: Mitee the warrior How likely are you to see
"zzz snort grumble roar"?
State transition matrix $A$ :

|  | Asleep | Calm | Angry | Hungry |
| :--- | :--- | :--- | :--- | :--- |
| Asleep | 0.5 | 0.2 | 0.1 | 0.2 |
| Calm | 0.4 | 0.3 | 0.1 | 0.2 |
| Angry | 0.1 | 0.2 | 0.6 | 0.1 |
| Hungry | 0.1 | 0.1 | 0.5 | 0.3 |



Output symbol matrix $B$ :

|  | Roar | Zzz | Snort | Grumble |
| :--- | :--- | :--- | :--- | :--- |
| Asleep | 0.0 | 0.9 | 0.1 | 0.0 |
| Calm | 0.0 | 0.0 | 0.8 | 0.2 |
| Angry | 1.0 | 0.0 | 0.0 | 0.0 |
| Hungry | 0.2 | 0.0 | 0.0 | 0.8 |

roar

Example: Mitee the warrior How likely are you to see
"zzz snort grumble roar"?
State transition matrix $A$ :

|  | Asleep | Calm | Angry | Hungry |
| :--- | :--- | :--- | :--- | :--- |
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|  | Asleep | Calm | Angry | Hungry |
| :--- | :--- | :--- | :--- | :--- |
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| Calm | 0.4 | 0.3 | 0.1 | 0.2 |
| Angry | 0.1 | 0.2 | 0.6 | 0.1 |
| Hungry | 0.1 | 0.1 | 0.5 | 0.3 |

Initial state probabilities $\Pi$ :

| Asleep | Calm | Angry | Hungry |
| :--- | :--- | :--- | :--- |
| 0.3 | 0.3 | 0.2 | 0.2 |

Output symbol matrix $B$ :

|  | Roar | Zzz | Snort | Grumble |
| :--- | :--- | :--- | :--- | :--- |
| Asleep | 0.0 | 0.9 | 0.1 | 0.0 |
| Calm | 0.0 | 0.0 | 0.8 | 0.2 |
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| Hungry | 0.1 | 0.1 | 0.5 | 0.3 |

Initial state probabilities $\Pi$ :

| Asleep | Calm | Angry | Hungry |
| :--- | :--- | :--- | :--- |
| 0.3 | 0.3 | 0.2 | 0.2 |

Output symbol matrix $B$ :

|  | Roar | Zzz | Snort | Grumble |
| :--- | :--- | :--- | :--- | :--- |
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| Calm | 0.0 | 0.0 | 0.8 | 0.2 |
| Angry | 1.0 | 0.0 | 0.0 | 0.0 |
| Hungry | 0.2 | 0.0 | 0.0 | 0.8 |



$$
(0.0135)(0.2)(0.2)=0.00054
$$

Example: Mitee the warrior How likely are you to see
"zzz snort grumble roar"?
State transition matrix $A$ :

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| :--- | :--- | :--- | :--- | :--- |
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| Calm | 0.4 | 0.3 | 0.1 | 0.2 |
| Angry | 0.1 | 0.2 | 0.6 | 0.1 |
| Hungry | 0.1 | 0.1 | 0.5 | 0.3 |

Initial state probabilities $\Pi$ :

| Asleep | Calm | Angry | Hungry |
| :--- | :--- | :--- | :--- |
| 0.3 | 0.3 | 0.2 | 0.2 |

Output symbol matrix $B$ :

|  | Roar | Zzz | Snort | Grumble |
| :--- | :--- | :--- | :--- | :--- |
| Asleep | 0.0 | 0.9 | 0.1 | 0.0 |
| Calm | 0.0 | 0.0 | 0.8 | 0.2 |
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| Calm | 0.4 | 0.3 | 0.1 | 0.2 |
| Angry | 0.1 | 0.2 | 0.6 | 0.1 |
| Hungry | 0.1 | 0.1 | 0.5 | 0.3 |

Initial state probabilities $\Pi$ :

| Asleep | Calm | Angry | Hungry |
| :--- | :--- | :--- | :--- |
| 0.3 | 0.3 | 0.2 | 0.2 |

Output symbol matrix $B$ :

|  | Roar | Zzz | Snort | Grumble |
| :--- | :--- | :--- | :--- | :--- |
| Asleep | 0.0 | 0.9 | 0.1 | 0.0 |
| Calm | 0.0 | 0.0 | 0.8 | 0.2 |
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| Hungry | 0.2 | 0.0 | 0.0 | 0.8 |



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| Hungry | 0.1 | 0.1 | 0.5 | 0.3 |

Initial state probabilities $\Pi$ :

| Asleep | Calm | Angry | Hungry |
| :--- | :--- | :--- | :--- |
| 0.3 | 0.3 | 0.2 | 0.2 |

Output symbol matrix $B$ :

|  | Roar | Zzz | Snort | Grumble |
| :--- | :--- | :--- | :--- | :--- |
| Asleep | 0.0 | 0.9 | 0.1 | 0.0 |
| Calm | 0.0 | 0.0 | 0.8 | 0.2 |
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| Angry | 0.1 | 0.2 | 0.6 | 0.1 |
| Hungry | 0.1 | 0.1 | 0.5 | 0.3 |

Initial state probabilities $\Pi$ :

| Asleep | Calm | Angry | Hungry |
| :--- | :--- | :--- | :--- |
| 0.3 | 0.3 | 0.2 | 0.2 |

Output symbol matrix $B$ :

|  | Roar | Zzz | Snort | Grumble |
| :--- | :--- | :--- | :--- | :--- |
| Asleep | 0.0 | 0.9 | 0.1 | 0.0 |
| Calm | 0.0 | 0.0 | 0.8 | 0.2 |
| Angry | 1.0 | 0.0 | 0.0 | 0.0 |
| Hungry | 0.2 | 0.0 | 0.0 | 0.8 |

grumble roar
$(0.0432)(0.2)(0.8)=$ 0.00691

Example: Mitee the warrior How likely are you to see
"zzz snort grumble roar"?
State transition matrix $A$ :

|  | Asleep | Calm | Angry | Hungry |
| :--- | :--- | :--- | :--- | :--- |
| Asleep | 0.5 | 0.2 | 0.1 | 0.2 |
| Calm | 0.4 | 0.3 | 0.1 | 0.2 |
| Angry | 0.1 | 0.2 | 0.6 | 0.1 |
| Hungry | 0.1 | 0.1 | 0.5 | 0.3 |

Initial state probabilities $\Pi$ :

| Asleep | Calm | Angry | Hungry |
| :--- | :--- | :--- | :--- |
| 0.3 | 0.3 | 0.2 | 0.2 |

Output symbol matrix $B$ :

|  | Roar | Zzz | Snort | Grumble |
| :--- | :--- | :--- | :--- | :--- |
| Asleep | 0.0 | 0.9 | 0.1 | 0.0 |
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| :--- | :--- | :--- | :--- | :--- |
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| Hungry | 0.1 | 0.1 | 0.5 | 0.3 |

Initial state probabilities $\Pi$ :

| Asleep | Calm | Angry | Hungry |
| :--- | :--- | :--- | :--- |
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Output symbol matrix $B$ :

|  | Roar | Zzz | Snort | Grumble |
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Initial state probabilities $\Pi$ :

| Asleep | Calm | Angry | Hungry |
| :--- | :--- | :--- | :--- |
| 0.3 | 0.3 | 0.2 | 0.2 |

Output symbol matrix $B$ :

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| Calm | 0.0 | 0.0 | 0.8 | 0.2 |
| Angry | 1.0 | 0.0 | 0.0 | 0.0 |
| Hungry | 0.2 | 0.0 | 0.0 | 0.8 |


$0.00259 * 0.2 * 0.2=0.000104$

Example: Mitee the warrior How likely are you to see
"zzz snort grumble roar"?
State transition matrix $A$ :

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| :--- | :--- | :--- | :--- | :--- |
| Asleep | 0.5 | 0.2 | 0.1 | 0.2 |
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| Angry | 0.1 | 0.2 | 0.6 | 0.1 |
| Hungry | 0.1 | 0.1 | 0.5 | 0.3 |


$0.00691 * 0.3 * 0.2=0.000415$

Example: Mitee the warrior How likely are you to see
"zzz snort grumble roar"?
State transition matrix $A$ :

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Initial state probabilities $\Pi$ :

| Asleep | Calm | Angry | Hungry |
| :--- | :--- | :--- | :--- |
| 0.3 | 0.3 | 0.2 | 0.2 |

Output symbol matrix $B$ :

|  | Roar | Zzz | Snort | Grumble |
| :--- | :--- | :--- | :--- | :--- |
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Initial state probabilities $\Pi$ :

| Asleep | Calm | Angry | Hungry |
| :--- | :--- | :--- | :--- |
| 0.3 | 0.3 | 0.2 | 0.2 |

Output symbol matrix $B$ :

|  | Roar | Zzz | Snort | Grumble |
| :--- | :--- | :--- | :--- | :--- |
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| Angry | 0.1 | 0.2 | 0.6 | 0.1 |
| Hungry | 0.1 | 0.1 | 0.5 | 0.3 |

Initial state probabilities $\Pi$ :

| Asleep | Calm | Angry | Hungry |
| :--- | :--- | :--- | :--- |
| 0.3 | 0.3 | 0.2 | 0.2 |

Output symbol matrix $B$ :

|  | Roar | Zzz | Snort | Grumble |
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| Asleep | 0.0 | 0.9 | 0.1 | 0.0 |
| Calm | 0.0 | 0.0 | 0.8 | 0.2 |
| Angry | 1.0 | 0.0 | 0.0 | 0.0 |
| Hungry | 0.2 | 0.0 | 0.0 | 0.8 |



Given this, is the most likely state sequence just the one whose states are most probable at every point in time?

## This worked out...



Given this, is the most likely state sequence just the one whose states are most probable at every point in time?

## But imagine the transition probabilities were slightly different



Given this, is the most likely state sequence just the one whose states are most probable at every point in time?

## But imagine the transition probabilities were slightly different



Given this, is the most likely state sequence just the one whose states are most probable at every point in time?

## But imagine the transition probabilities were slightly different



Given this, is the most likely state sequence just the one whose states are most probable at every point in time?

## But imagine the transition probabilities were slightly different



In order to calculate the most likely state sequence, you need to find the maximum transition at each point, get to the end, and then backtrack through

This algorithm - finding all of the forward probabilities (maxima, not sums), and then backtracking - is called the Viterbi algorithm.

## Three fundamental questions for HMMs

- Given a model $M=(A, B, \Pi)$, how do we efficiently compute how likely a certain observation is?
- Given a sequence of observations $Y$ and a model $M$, how do we infer the state sequence that best explains the observations?
$\Rightarrow$ Given an observation sequence $Y$ and a space of possible models found by varying the model parameters $M=$ $(A, B, \Pi)$, how do we find the model that best explains the observed data?


[^2]
## Three fundamental questions for HMMs

I'll give the main idea of how it works, but not all of the nitty-gritty detail. You don't need to be able to implement this - I just want to get you started in case you ever want to.
$\Rightarrow$ Given an observation sequence $Y$ and a space of possible models found by varying the model parameters $M=$ ( $A, B, \Pi$ ), how do we find the model that best explains the observed data?

[^3]
## Baum-Welch algorithm

## Basic idea: This is just an EM algorithm! But instead of:

## Assignment step (E-step):

Calculate the likelihood of each data point in each cluster, assuming the cluster is a Gaussian with the current mean, standard deviation, and weight

## Update step (M-step):

Recalculate the means

Recalculate the standard deviations

Recalculate the weights

$$
r_{k}^{(n)}=\frac{w_{k} \frac{1}{\prod_{i=1}^{I} \sqrt{2 \pi} \sigma_{i}^{(k)}} \exp \left(-\sum_{i=1}^{I}\left(m_{i}^{(k)}-x_{i}^{(n)}\right)^{2} / 2\left(\sigma_{i}^{(k)}\right)^{2}\right)}{\sum_{k^{\prime}} w_{k^{\prime}} \frac{1}{\prod_{i=1}^{I} \sqrt{2 \pi} \sigma_{i}^{\left(k^{\prime}\right)}} \exp \left(-\sum_{i=1}^{I}\left(m_{i}^{\left(k^{\prime}\right)}-x_{i}^{(n)}\right)^{2} / 2\left(\sigma_{i}^{\left(k^{\prime}\right)}\right)^{2}\right)}
$$

$$
\begin{aligned}
\mathbf{m}^{(k)} & =\frac{\sum_{k} r_{k}^{(n)} \mathbf{x}^{(n)}}{\sum_{n} r_{k}^{(n)}} \\
\sigma_{k}^{2} & =\frac{\sum_{n} r_{k}^{(n)}\left(x_{i}^{(n)}-m_{i}^{(k)}\right)^{2}}{\sum_{n} r_{k}^{(n)}} \\
w_{k} & =\frac{\sum_{n} r_{k}^{(n)}}{\sum_{k} \sum_{n} r_{k}^{(n)}}
\end{aligned}
$$

## Baum-Welch algorithm

## Basic idea: This is just an EM algorithm! But instead of:

## Assignment step (E-step):

Calculate the probability of the observation sequence given the current model ( $A, B, \Pi$ )

```
Update step (M-step):
```

> Forward algorithm

Recalculate $A$
Recalculate $B$
Recalculate $\Pi$

$$
\begin{gathered}
a_{i j}=\frac{\text { expected number of transitions from state } i \text { to } j}{\text { Expected number of transitions from state } i} \\
b_{i j k} \frac{\text { expected \# of transitions from state } i \text { to } j \text { with } k \text { observed }}{\text { Expected number of transitions from } i \text { to } j} \\
\pi_{i}=\text { expected frequency in state } i \text { at time } t=1
\end{gathered}
$$

## Baum-Welch algorithm

- Because it is an EM algorithm, it has the same properties:

1. Guaranteed (fairly rapid) convergence, but only to local maxima, not global maxima
2. Dependence on initial values. In practice, it is especially important to have good starting points for the output parameters $B$; estimates of $A$ are fairly robust to initial starting point.

## Stepping back a bit...

We have defined what a Hidden Markov Model (HMM) is, and proposed it as a better model for language than an n-gram model (i.e., a standard Markov Model)

We have seen in detail how it is possible to calculate the most probable path of hidden states in an HMM, and the probability of an observation

We have seen in brief how it is possible to figure out (imperfectly) what the most probable set of transition probabilities $(A, B, \Pi)$ are, given a set of observations

## Stepping back a bit...

We have defined what a Hidden Markov Model (HMM) is, and proposed it as a better model for language than an n-gram model (i.e., a standard Markov Model)


But are HMMs indeed a good model of language?

Not really.

## Plan

, Last time: introduction to HMMs

- Limitations of n-grams applied to language
- Basics of HMMs
- Today: finishing HMMs, and more complex structures
- Determining the likelihood of a given observation
- Calculating the most likely state sequence
- Finding the best HMM for given data
- More complex models of language


## Still have a parameter explosion problem


(0.5) verb $\rightarrow$ eats
(0.5) verb $\rightarrow$ runs
(0.3) pro $\rightarrow$ he
(0.3) pro $\rightarrow$ she
(0.4) pro $\rightarrow$ it
(0.7) det $\rightarrow$ the
(0.3) det $\rightarrow \mathrm{a}$
(0.4) noun $\rightarrow$ boy
(0.4) noun $\rightarrow$ dog
(0.2) noun $\rightarrow$ tiger
(1.0) adj $\rightarrow$ happy

## Still have a parameter explosion problem

Suppose you want to make it able to produce: The students write


Now it also produces:
The dog write
A students runs
The students eats
He write

## Still have a parameter explosion problem

As before, you have to add new states to the model to solve this problem

## Still have a parameter explosion problem


(0.5) verb $_{\mathrm{S}} \rightarrow$ eats
(0.5) verb $_{\mathrm{S}} \rightarrow$ runs
(1.0) verb $_{\mathrm{P}} \rightarrow$ write
(0.3) $\mathrm{pro}_{\mathrm{S}} \rightarrow$ he
(0.3) $\mathrm{pro}_{\mathrm{S}} \rightarrow$ she
(0.4) $\mathrm{pro}_{\mathrm{S}} \rightarrow$ it
(0.7) det $\rightarrow$ the
(0.3) det $\rightarrow \mathrm{a}$
(0.4) noun $_{S} \rightarrow$ boy
(0.4) noun $_{\text {S }} \rightarrow$ dog
(0.2) noun $_{S} \rightarrow$ tiger
(1.0) noun $_{P} \rightarrow$ students
(1.0) adj $\rightarrow$ happy

## Still have a parameter explosion problem

It's made worse if we make the grammar even more complicated


## Still have a parameter explosion problem

However, you might notice a regularity in this grammmar


## Still have a parameter explosion problem

However, you might notice a regularity in this grammmar
phrase


## Still have a parameter explosion problem

Need to specify what
each phrase means

$$
\begin{aligned}
& \mathrm{NP}_{\mathrm{S}} \rightarrow \operatorname{pro}_{\mathrm{S}} \\
& \mathrm{NP}_{\mathrm{S}} \rightarrow \operatorname{det} \text { noun }_{\mathrm{S}} \\
& \mathrm{NP}_{\mathrm{P}} \rightarrow \operatorname{pro}_{\mathrm{P}} \\
& \mathrm{NP}_{\mathrm{P}} \rightarrow \operatorname{det} \text { noun }_{\mathrm{P}}
\end{aligned}
$$



## Still have a parameter explosion problem

A grammar like this, which is formed by "clustering" states of an HMM, has phrase structure

$$
\begin{aligned}
& \mathrm{NP}_{\mathrm{S}} \rightarrow \operatorname{pro}_{\mathrm{S}} \\
& \mathrm{NP}_{\mathrm{S}} \rightarrow \operatorname{det} \text { noun }_{\mathrm{S}} \\
& \mathrm{NP}_{\mathrm{P}} \rightarrow \operatorname{pro}_{\mathrm{P}} \\
& \mathrm{NP}_{\mathrm{P}} \rightarrow \operatorname{det} \text { noun }_{\mathrm{P}}
\end{aligned}
$$



## Still have a parameter explosion problem

We can even form phrases of other phrases - if we do that, we say the grammar has hierarchical phrase structure

```
VP
VP
NP
NP
NP
NP
```



## This is a context-free grammar (CFG)

Context-free grammars can be formed from an HMM by clustering states into phrases. They have hierarchical phrase structure: a key feature of language

$$
\begin{aligned}
& \mathrm{S} \rightarrow \mathrm{NP}_{\mathrm{S}} \mathrm{VP}_{\mathrm{S}} \\
& \mathrm{~S} \rightarrow \mathrm{NP}_{\mathrm{P}} \mathrm{VP}_{\mathrm{P}} \\
& \mathrm{VP}_{\mathrm{S}} \rightarrow \mathrm{verb}_{\mathrm{S}} \mathrm{NP}_{\mathrm{S}} \\
& \mathrm{VP}_{\mathrm{P}} \rightarrow \operatorname{verb}_{\mathrm{P}} \mathrm{NP}_{\mathrm{P}} \\
& \mathrm{NP}_{\mathrm{S}} \rightarrow \operatorname{pro}_{\mathrm{S}} \\
& \mathrm{NP}_{\mathrm{S}} \rightarrow \operatorname{det} \text { noun }_{\mathrm{S}} \\
& \mathrm{NP}_{\mathrm{P}} \rightarrow \operatorname{pro}_{\mathrm{P}} \\
& \mathrm{NP}_{\mathrm{P}} \rightarrow \operatorname{det} \text { noun }_{\mathrm{P}}
\end{aligned}
$$

## Formal definition of CFG (or PCFG)

A PCFG $G$ with a vocabulary $V$ and $n$ nonterminals consists of:

- A set of terminals, $\left\{w^{k}\right\}, k=1, \ldots, V \quad\{$ a, the, boy, tiger, dog, school, it, she, her, him, he...\}
- A set of nonterminals, $\left\{N^{i}\right\}, i=1, \ldots, n$ $\left\{S_{,}, \mathrm{VP}_{\mathrm{S}}, \mathrm{VP}_{\mathrm{P}}, \mathrm{NP}_{\mathrm{S}}, \mathrm{NP}_{\mathrm{P}}, \mathrm{PRO}_{\mathrm{S}}, \mathrm{D}, \mathrm{N}_{\mathrm{S}}, \mathrm{PRO}_{\mathrm{P}}, \mathrm{N}_{\mathrm{P}}, \mathrm{V}_{\mathrm{S}}, \mathrm{A}, \mathrm{V}_{\mathrm{P}}\right\}$ S
- A designated start symbol, $N^{1}$
- A set of rules, $\left\{N^{i} \rightarrow \zeta^{j}\right\}$, where $\zeta^{j}$ is a sequence of terminals and nonterminals
- A corresponding set of probabilities on rules such that $\forall i \sum_{j} P\left(N^{i} \rightarrow \zeta^{j}\right)=1$
(0.3) $\mathrm{N}_{\mathrm{S}} \rightarrow$ boy
(0.3) $\mathrm{N}_{\mathrm{S}} \rightarrow$ tiger
(0.3) $\mathrm{N}_{\mathrm{S}} \rightarrow \operatorname{dog}$
(0.2) $\mathrm{N}_{\mathrm{P}} \rightarrow$ boy
(0.2) $\mathrm{N}_{\mathrm{P}} \rightarrow$ tiger
(0.2) $\mathrm{N}_{\mathrm{P}} \rightarrow \operatorname{dog}$
(0.15) $\mathrm{N}_{\mathrm{P}} \rightarrow$ school
(0.15) $\mathrm{N}_{\mathrm{P}} \rightarrow$ house
(0.5) $\mathrm{V}_{\mathrm{S}} \rightarrow$ sees
(0.5) $\mathrm{V}_{\mathrm{S}} \rightarrow$ cleans
(0.5) $\mathrm{V}_{\mathrm{P}} \rightarrow$ see
(0.5) $\mathrm{V}_{\mathrm{P}} \rightarrow$ clean
(1.0) $\mathrm{A} \rightarrow$ happy


## Example sentences

The boys clean the house

He sees the dog

## She cleans it

The happy dogs see a tiger
(0.5) $\mathrm{S} \rightarrow \mathrm{NP}_{\mathrm{S}} \mathrm{VP}_{\mathrm{S}}$
(0.5) $\mathrm{S} \rightarrow \mathrm{NP}_{\mathrm{P}} \mathrm{VP}_{\mathrm{P}}$
(1.0) $\mathrm{VP}_{\mathrm{S}} \rightarrow \mathrm{V}_{\mathrm{S}} \mathrm{NP}_{\mathrm{S}}$
(1.0) $\mathrm{VP}_{\mathrm{P}} \rightarrow \mathrm{V}_{\mathrm{P}} \mathrm{NP}_{\mathrm{P}}$
(0.7) $\mathrm{NP}_{\mathrm{S}} \rightarrow \mathrm{PRO}_{\mathrm{S}}$
(0.3) $\mathrm{NP}_{\mathrm{S}} \rightarrow \mathrm{D} \mathrm{N}_{\mathrm{S}}$
(0.7) $\mathrm{NP}_{\mathrm{P}} \rightarrow \mathrm{PRO}_{\mathrm{P}}$
(0.3) $\mathrm{NP}_{\mathrm{P}} \rightarrow \mathrm{D} \mathrm{N}_{\mathrm{P}}$
(0.3) $\mathrm{PRO}_{\mathrm{S}} \rightarrow$ he
(0.3) $\mathrm{PRO}_{\mathrm{S}} \rightarrow$ she
(0.4) $\mathrm{PRO}_{\mathrm{S}} \rightarrow$ it
(0.3) $\mathrm{PRO}_{\mathrm{P}} \rightarrow$ her
(0.3) $\mathrm{PRO}_{\mathrm{P}} \rightarrow$ him
(0.4) $\mathrm{PRO}_{\mathrm{P}} \rightarrow$ it
(0.3) D $\rightarrow$ a
(0.7) $\mathrm{D} \rightarrow$ the
(0.1) $\mathrm{N}_{\mathrm{S}} \rightarrow \mathrm{AN}_{\mathrm{S}}$
(0.1) $\mathrm{N}_{\mathrm{P}} \rightarrow \mathrm{A} \mathrm{N}_{\mathrm{P}}$
(0.3) $\mathrm{N}_{\mathrm{S}} \rightarrow$ boy
(0.3) $\mathrm{N}_{\mathrm{S}} \rightarrow$ tiger
(0.3) $\mathrm{N}_{\mathrm{S}} \rightarrow$ dog
(0.2) $\mathrm{N}_{\mathrm{P}} \rightarrow$ boy
(0.2) $\mathrm{N}_{\mathrm{P}} \rightarrow$ tiger
(0.2) $\mathrm{N}_{\mathrm{P}} \rightarrow$ dog
(0.15) $\mathrm{N}_{\mathrm{P}} \rightarrow$ school
(0.15) $\mathrm{N}_{\mathrm{P}} \rightarrow$ house
$(0.5) \mathrm{V}_{\mathrm{S}} \rightarrow$ sees
(0.5) $\mathrm{V}_{\mathrm{S}} \rightarrow$ cleans
(0.5) $\mathrm{V}_{\mathrm{P}} \rightarrow$ see
(0.5) $\mathrm{V}_{\mathrm{P}} \rightarrow$ clean
(1.0) A $\rightarrow$ happy

## Example sentences

The boys clean the house
She cleans
He sees the dog

The happy dogs see a tiger

It is relatively easy to expand on this and add new types of sentences
(0.5) $\mathrm{S} \rightarrow \mathrm{NP}_{\mathrm{S}} \mathrm{VP}_{\mathrm{S}}$
(0.5) $\mathrm{S} \rightarrow \mathrm{NP}_{\mathrm{P}} \mathrm{VP}_{\mathrm{P}}$
(0.5) $\mathrm{VP}_{\mathrm{S}} \rightarrow \mathrm{V}_{\mathrm{S}} \mathrm{NP}_{\mathrm{S}}$
(0.5) $\mathrm{VP}_{\mathrm{S}} \rightarrow \mathrm{V}_{\mathrm{S}}$
(0.5) $\mathrm{VP}_{\mathrm{P}} \rightarrow \mathrm{V}_{\mathrm{P}} \mathrm{NP}_{\mathrm{P}}$
(0.5) $\mathrm{VP}_{\mathrm{P}} \rightarrow \mathrm{V}_{\mathrm{P}}$
(0.7) $\mathrm{NP}_{\mathrm{S}} \rightarrow \mathrm{PRO}_{\mathrm{S}}$
(0.3) $\mathrm{NP}_{\mathrm{S}} \rightarrow \mathrm{D} \mathrm{N}_{\mathrm{S}}$
(0.7) $\mathrm{NP}_{\mathrm{P}} \rightarrow \mathrm{PRO}_{\mathrm{P}}$
(0.3) $\mathrm{NP}_{\mathrm{P}} \rightarrow \mathrm{D} \mathrm{N}_{\mathrm{P}}$
(0.3) $\mathrm{PRO}_{\mathrm{S}} \rightarrow$ he
(0.3) $\mathrm{PRO}_{\mathrm{S}} \rightarrow$ she
(0.4) $\mathrm{PRO}_{\mathrm{S}} \rightarrow$ it
(0.3) $\mathrm{PRO}_{\mathrm{P}} \rightarrow$ her
(0.3) $\mathrm{PRO}_{\mathrm{P}} \rightarrow$ him
(0.4) $\mathrm{PRO}_{\mathrm{P}} \rightarrow$ it
(0.3) $\mathrm{D} \rightarrow \mathrm{a}$
(0.7) $\mathrm{D} \rightarrow$ the
(0.1) $\mathrm{N}_{\mathrm{S}} \rightarrow \mathrm{AN}_{\mathrm{S}}$
(0.1) $\mathrm{N}_{\mathrm{P}} \rightarrow \mathrm{AN}_{\mathrm{P}}$
(0.2) $\mathrm{N}_{\mathrm{P}} \rightarrow$ boy
(0.2) $\mathrm{N}_{\mathrm{P}} \rightarrow$ tiger
(0.2) $\mathrm{N}_{\mathrm{P}} \rightarrow \operatorname{dog}$
$(0.15) \mathrm{N}_{\mathrm{P}} \rightarrow$ school
(0.15) $\mathrm{N}_{\mathrm{P}} \rightarrow$ house
(0.5) $\mathrm{V}_{\mathrm{S}} \rightarrow$ sees
(0.5) $\mathrm{V}_{\mathrm{S}} \rightarrow$ cleans
(0.5) $\mathrm{V}_{\mathrm{P}} \rightarrow$ see
(0.5) $\mathrm{V}_{\mathrm{P}} \rightarrow$ clean
(1.0) $\mathrm{A} \rightarrow$ happy

## Example sentences

The boys behind the school clean the house.

He sees the dog with it

She sees the dog behind a tiger

| (0.5) $\mathrm{S} \rightarrow \mathrm{NP}_{\mathrm{S}} \mathrm{VP}_{\mathrm{S}}$ | (0.5) $\mathrm{PP} \rightarrow \mathrm{PNP}_{\mathrm{S}}$ |  |  |
| :---: | :---: | :---: | :---: |
| (0.5) $\mathrm{S} \rightarrow \mathrm{NP}_{\mathrm{P}} \mathrm{VP}_{\mathrm{P}}$ | (0.5) $\mathrm{PP} \rightarrow \mathrm{P} \mathrm{NP}_{\mathrm{P}}$ | (0.3) | $\mathrm{N}_{\mathrm{S}} \rightarrow$ boy |
| (0.4) $\mathrm{VP}_{\mathrm{S}} \rightarrow \mathrm{V}_{\mathrm{S}} \mathrm{NP}_{\mathrm{S}}$ | (0.3) $\mathrm{PRO}_{\mathrm{S}} \rightarrow$ he | (0.3) | $\mathrm{N}_{\mathrm{S}} \rightarrow$ tiger |
| (0.2) $\mathrm{VP}_{\mathrm{S}} \rightarrow \mathrm{V}_{\mathrm{S}} \mathrm{NP}_{\mathrm{S}} \mathrm{PP}$ | (0.3) $\mathrm{PRO}_{\mathrm{S}} \rightarrow$ she | (0.3) | $\mathrm{N}_{\mathrm{S}} \rightarrow \operatorname{dog}$ |
| (0.4) $\mathrm{VP}_{\mathrm{S}} \rightarrow \mathrm{V}_{\mathrm{S}}$ | (0.4) $\mathrm{PRO}_{\mathrm{S}} \rightarrow$ it | (0.2) | $\mathrm{N}_{\mathrm{P}} \rightarrow$ boy |
| (0.4) $\mathrm{VP}_{\mathrm{P}} \rightarrow \mathrm{V}_{\mathrm{P}} \mathrm{NP}_{\mathrm{P}}$ | (0.3) $\mathrm{PRO}_{\mathrm{P}} \rightarrow$ her | (0.2) | $\mathrm{N}_{\mathrm{P}} \rightarrow$ tiger |
| (0.2) $\mathrm{VP}_{\mathrm{P}} \rightarrow \mathrm{V}_{\mathrm{P}} \mathrm{NP}_{\mathrm{P}} \mathrm{PP}$ | (0.3) $\mathrm{PRO}_{\mathrm{P}} \rightarrow \mathrm{him}$ | (0.2) | $\mathrm{N}_{\mathrm{P}} \rightarrow \operatorname{dog}$ |
| (0.4) $\mathrm{VP}_{\mathrm{P}} \rightarrow \mathrm{V}_{\mathrm{P}}$ | (0.4) $\mathrm{PRO}_{\mathrm{P}} \rightarrow$ it | (0.15) | $\mathrm{N}_{\mathrm{P}} \rightarrow$ school |
| (0.6) $\mathrm{NP}_{\mathrm{S}} \rightarrow \mathrm{PRO}_{\mathrm{S}}$ | (0.3) $\mathrm{D} \rightarrow \mathrm{a}$ | (0.15) | $\mathrm{N}_{\mathrm{P}} \rightarrow$ house |
| (0.3) $\mathrm{NP}_{\mathrm{S}} \rightarrow \mathrm{DNS}_{\mathrm{S}}$ | (0.7) $\mathrm{D} \rightarrow$ the | (0.5) | $\mathrm{V}_{\mathrm{S}} \rightarrow$ sees |
| (0.6) $\mathrm{NP}_{\mathrm{P}} \rightarrow \mathrm{PRO}_{\mathrm{P}}$ | (0.1) $\mathrm{N}_{\mathrm{S}} \rightarrow \mathrm{AN}_{\mathrm{S}}$ | (0.5) | $\mathrm{V}_{\mathrm{S}} \rightarrow$ cleans |
| (0.3) $\mathrm{NP}_{\mathrm{P}} \rightarrow \mathrm{D} \mathrm{N}_{\mathrm{P}}$ | (0.1) $\mathrm{N}_{\mathrm{P}} \rightarrow \mathrm{A} \mathrm{N}_{\mathrm{P}}$ | (0.5) | $\mathrm{V}_{\mathrm{P}} \rightarrow$ see |
| (0.1) $\mathrm{NP}_{\mathrm{S}} \rightarrow \mathrm{NP}_{\mathrm{S}} \mathrm{PP}$ | (0.5) $\mathrm{P} \rightarrow$ with | (0.5) | $\mathrm{V}_{\mathrm{P}} \rightarrow$ clean |
| $(0.1) \mathrm{NP}_{\mathrm{P}} \rightarrow \mathrm{NP}_{\mathrm{P}} \mathrm{PP}$ | (0.5) $\mathrm{P} \rightarrow$ behind | (1.0) | $\mathrm{A} \rightarrow$ happy |

## Context free grammars

Yield sentences with hierarchical phrase structure, in which phrases can be nestled hierarchically within one another.

This is known as a parse tree for that sentence, and parsing is the act of figuring out the parse trees for a given sentence.

## Context free grammars

Many sentences are ambiguous - they have multiple possible parse trees


## Context free grammars

Many sentences are ambiguous - they have multiple possible parse trees


## Context free grammars

This can often be a source of unintentional humour

```
Don't let worry kill you - let the church help.
        Ingres enjoyed painting his models nude.
            Visiting relatives can be boring.
```

            Iraqi head seeks arms
        Grandmother of eight makes hole in one
        Two sisters reunite after eighteen years at
        checkout counter
    Dr. Ruth to talk about sex with newspaper editors

## Context free grammars

These sorts of misunderstandings are one of the pieces of evidence suggesting that the underlying parse trees are psychologically "real"

## Using context-free grammars

The probability of a parse is the probability of each of the rules used to generate that parse $0.5 * 0.6 * 0.3 * 0.2 * 0.5 * 0.3 * 0.7 * 0.3 * 0.5 * 0.5 * 0.3 * 0.7 * 0.2=5.95 \mathrm{e}-6$

(0.5) $\mathrm{S} \rightarrow \mathrm{NP}_{\mathrm{S}} \mathrm{VP}_{\mathrm{S}}$
$(0.6) \mathrm{NP}_{\mathrm{S}} \rightarrow \mathrm{PRO}_{\mathrm{S}}$
(0.3) $\mathrm{PRO}_{\mathrm{S}} \rightarrow$ she
(0.2) $\mathrm{VP}_{\mathrm{S}} \rightarrow \mathrm{V}_{\mathrm{S}} \mathrm{NP}_{\mathrm{S}} \mathrm{PP}$
$(0.5) \mathrm{V}_{\mathrm{S}} \rightarrow$ sees
(0.3) $\mathrm{NP}_{\mathrm{S}} \rightarrow \mathrm{D} \mathrm{N}_{\mathrm{S}}$
(0.7) D $\rightarrow$ the
(0.3) $\mathrm{N}_{\mathrm{S}} \rightarrow$ man
$(0.5) \mathrm{PP} \rightarrow \mathrm{P} \mathrm{NP}_{\mathrm{S}}$
(0.5) $\mathrm{P} \rightarrow$ with
(0.7) $\mathrm{D} \rightarrow$ the
(0.2) $\mathrm{N}_{\mathrm{S}} \rightarrow$ telescope

## Using context-free grammars

If the sentence is ambiguous, you need to add the probabilities of each of the possible parses

$$
\begin{aligned}
& 0.5 * 0.6 * 0.3 * 0.2 * 0.5 * 0.3 * 0.7 * 0.3 * 0.5 * 0.5 * 0.3 * 0.7 * 0.2+ \\
& 0.5 * 0.6 * 0.3 * 0.4 * 0.5 * 0.3 * 0.3 * 0.7 * 0.3 * 0.5 * 0.5 * 0.3 * 0.7 * 0.2=9.52 \mathrm{e}-6
\end{aligned}
$$

(0.5) $\mathrm{S} \rightarrow \mathrm{NP}_{\mathrm{S}} \mathrm{VP}_{\mathrm{S}}$

(0.6) $\mathrm{NP}_{\mathrm{S}} \rightarrow \mathrm{PRO}_{\mathrm{S}}$
(0.3) $\mathrm{PRO}_{\mathrm{S}} \rightarrow$ she
$(0.2) \mathrm{VP}_{\mathrm{S}} \rightarrow \mathrm{V}_{\mathrm{S}} \mathrm{NP}_{\mathrm{S}} \mathrm{PP}$
(0.5) $\mathrm{V}_{\mathrm{S}} \rightarrow$ sees
(0.3) $\mathrm{NP}_{\mathrm{S}} \rightarrow \mathrm{D} \mathrm{N}_{\mathrm{S}}$
(0.7) $\mathrm{D} \rightarrow$ the
(0.3) $\mathrm{N}_{\mathrm{S}} \rightarrow$ man
(0.5) $\mathrm{PP} \rightarrow \mathrm{P} \mathrm{NP}_{\mathrm{S}}$
(0.5) $\mathrm{P} \rightarrow$ with
(0.7) $\mathrm{D} \rightarrow$ the
(0.2) $\mathrm{N}_{\mathrm{S}} \rightarrow$ telescope

## Using context-free grammars

## More massive grammar = more ambiguous sentences.

Grammars that are typically used in computational linguistics have many ambiguous parses.


## Using context-free grammars

A PCFG gives some idea of the plausibility of different parses; however, this is often not very linguistically accurate, since it doesn't take into account semantics (meaning) or local lexical context


## Using context-free grammars

Real language contains a lot of grammatical mistakes; PCFGs can be fairly robust to those, at the price of having many incorrect (but very low-probability) rules.

(0.5) $\mathrm{S} \rightarrow \mathrm{NP}_{\mathrm{S}} \mathrm{VP}_{\mathrm{S}}$
(0.6) $\mathrm{NP}_{\mathrm{S}} \rightarrow \mathrm{PRO}_{\mathrm{S}}$
(0.3) $\mathrm{PRO}_{\mathrm{S}} \rightarrow$ she
(0.4) $\mathrm{VP}_{\mathrm{S}} \rightarrow \mathrm{V}_{\mathrm{S}} \mathrm{NP}_{\mathrm{S}}$
(0.5) $\mathrm{V}_{\mathrm{S}} \rightarrow$ sees
$(0.29) \mathrm{NP}_{\mathrm{S}} \rightarrow \mathrm{D} \mathrm{N}_{\mathrm{S}}$
$(0.01) \mathrm{NP}_{\mathrm{S}} \rightarrow \mathrm{D} \mathrm{X} \mathrm{N}_{\mathrm{S}}$
(0.7) $\mathrm{D} \rightarrow$ the
(0.3) $\mathrm{N}_{\mathrm{S}} \rightarrow$ man
(0.5) $\mathrm{PP} \rightarrow \mathrm{P} \mathrm{NP}_{\mathrm{S}}$
(0.5) $\mathrm{P} \rightarrow$ with
(0.7) $\mathrm{D} \rightarrow$ the
(0.2) $\mathrm{N}_{\mathrm{S}} \rightarrow$ telescope
(1.0) $\mathrm{X} \rightarrow$ uh

## Using context-free grammars

CFGs are useful because:
They are tractable, and more realistic models of language than HMMs or n-grams

But we still use HMMs and n-grams because:
They are much more tractable, and scale better with large vocabularies.

In practice, most state-of-the-art stuff combines these different techniques to try to take advantage of the best aspects of each

## Summary

- Hidden Markov models: Markov models with hidden states (often corresponding to parts of speech) do better than n-grams, although still have parameter explosion problems



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- Baum-Welch algorithm: figure out the most likely model given a set of observations

```
Assignment step (E-step):
    Calculate the probability of the observation
sequence given the current model ( }A,B,\Pi\mathrm{ )
Update step (M-step):
```

Forward algorithm

Recalculate $A$
Recalculate $B$
Recalculate $\Pi$

$$
\begin{gathered}
a_{i j}=\frac{\text { expected number of transitions from state } i \text { to } j}{\text { Expected number of transitions from state } i} \\
b_{i j k}=\frac{\text { expected \# of transitions from state } i \text { to } j \text { with } k \text { observed }}{\text { Expected number of transitions from } i \text { to } j} \\
\pi_{i}=\text { expected frequency in state } i \text { at time } t=1
\end{gathered}
$$

## Summary

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Starting next time: switching gears again to how people use data. In particular, we'll talk about how the informativeness of data depends on how it was sampled and the structure of the hypotheses (and whether people are aware of this)

## Additional references (not required)

## HMMs

- Wikipedia entry on CFGs is also pretty good!
- Manning, C., \& Schutze, H. (1999). Foundations of statistical natural language processing. Chapter 11.
- Russell, S., \& Norvig, P. (1995). Artificial Intelligence: A modern approach. (This one is first edition, but all editions have good resources on grammars). Chapter 22


[^0]:    * You should be able to implement this; ** You don't need to be able to implement this

[^1]:    * You should be able to implement this;

[^2]:    * You should be able to implement this; ** You don’t need to be able to implement this

[^3]:    * You should be able to implement this; ** You don't need to be able to implement this

