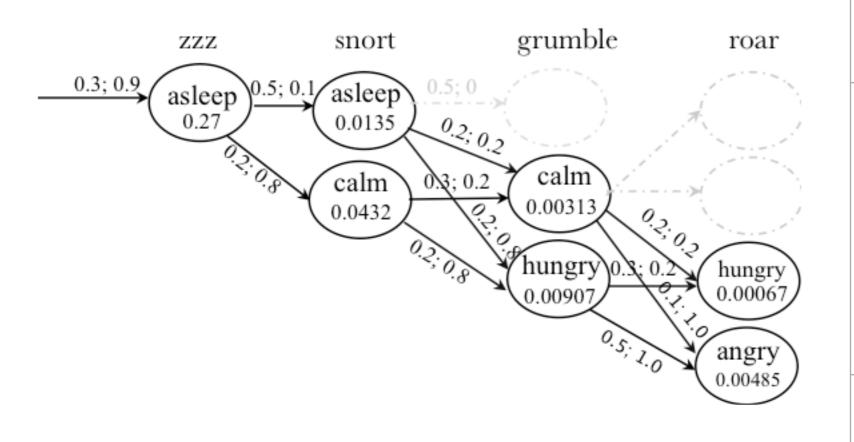
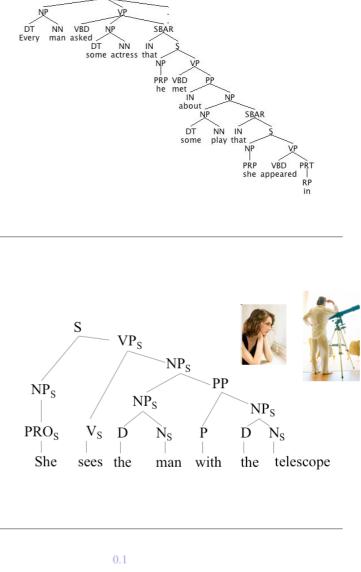
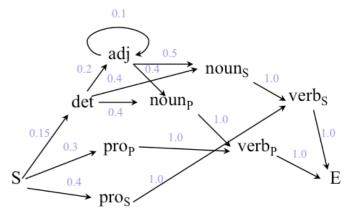
Computational Cognitive Science



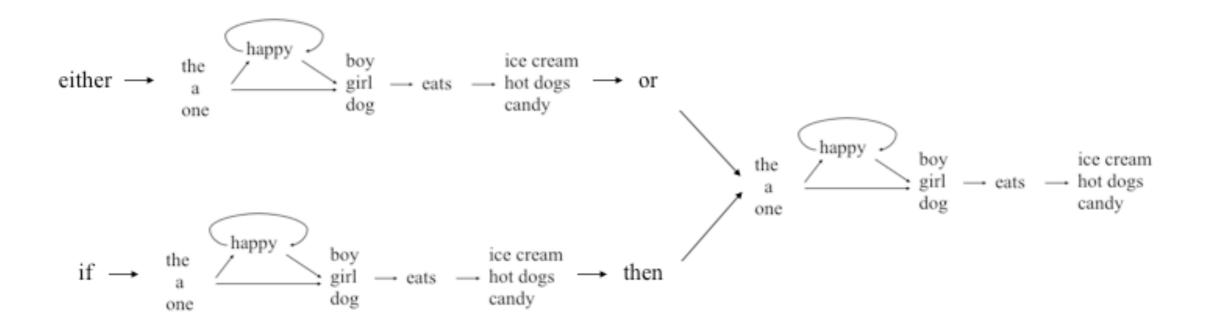


Lecture 19: HMMs and more complex grammars



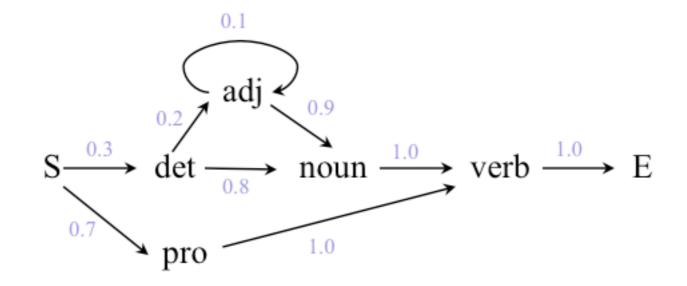


 Because of the problem of long-distance dependencies, Markov models are not good models of language: they need to be too large to capture its regularities



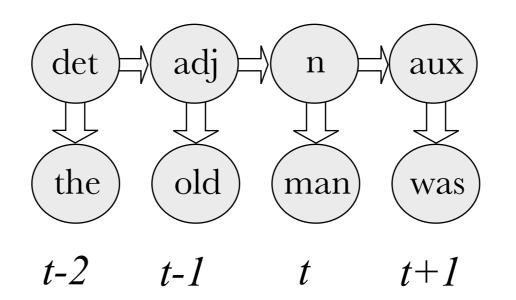
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- Grammars that incorporate parts of speech can be useful for greatly minimising the size of the grammar required
- Hidden Markov models, which involve hidden states that generate observations, can capture parts of speech
- We can use such models to generate sequences of observations in both linguistic and non-linguistic contexts

Plan

- Last time: introduction to HMMs
 - Limitations of n-grams applied to language
 - Basics of HMMs
- ▶ Today: finishing HMMs, and more complex structures
 - Determining the likelihood of a given observation
 - Calculating the most likely state sequence
 - Finding the best HMM for given data
 - More complex models of language

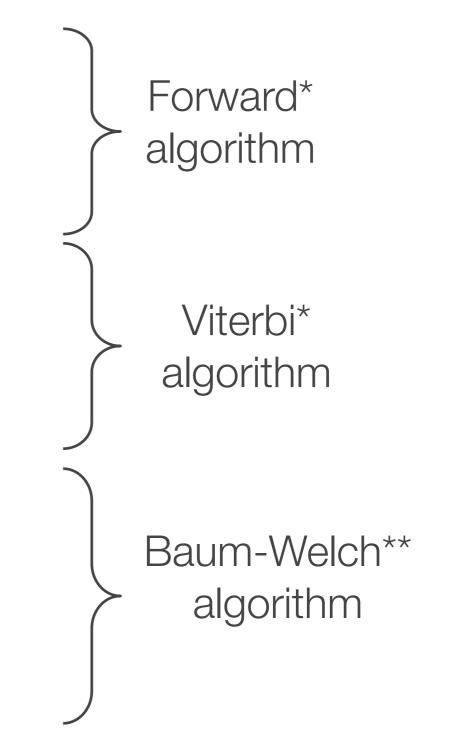
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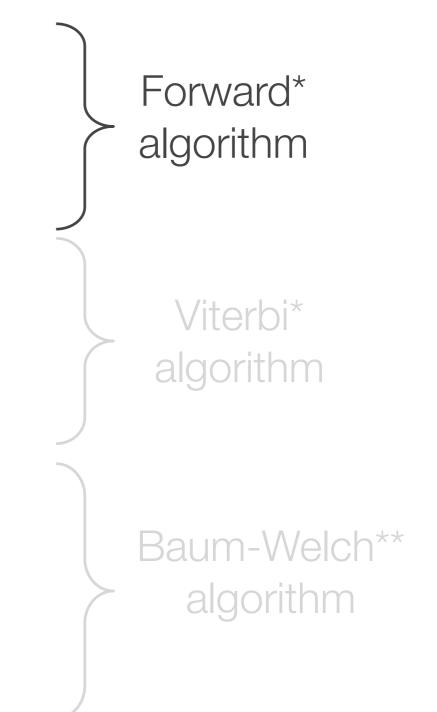
Three fundamental questions for HMMs

- Given a model M = (A,B,Π), how do we efficiently compute how likely a certain observation is?
- Given a sequence of observations Y and a model M, how do we infer the state sequence that best explains the observations?
- Given an observation sequence Y and a space of possible models found by varying the model parameters M = (A,B,Π), how do we find the model that best explains the observed data?



Three fundamental questions for HMMs

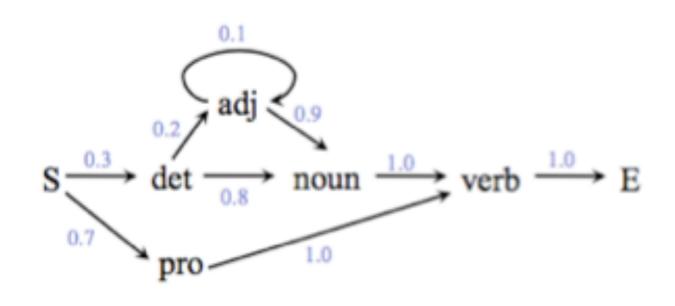
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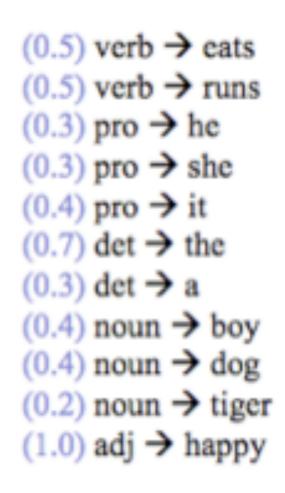


For any output sequence $Y = (y_1, ..., y_T)$ we can calculate the probability of observing it by summing over all possible sequences of hidden states that could have generated it:

$$p(Y) = \sum_{X} p(Y|X)p(X)$$

Example: simple language How likely are you to see "he eats"?





 $P(\text{ he eats } | A, B, \Pi)$ = P(pro|S) P(he|pro) P(verb|pro) P(eats| verb) P(E|verb) = 0.7 * 0.3 * 1.0 * 0.5 * 1.0 = 0.105

But that was easy, because there was just one way to generate that observation

Example: Mitee the warrior How likely are you to see "zzz snort"?

Initial state probabilities Π :

Asleep	Calm	Angry	Hungry
0.3	0.3	0.2	0.2

State transition matrix A:

	Asleep	Calm	Angry	Hungry
Asleep	0.5	0.2	0.1	0.2
Calm	0.4	0.3	0.1	0.2
Angry	0.1	0.2	0.6	0.1
Hungry	0.1	0.1	0.5	0.3

Output symbol matrix B:

	Roar	Zzz	Snort	Grumble
Asleep	0.0	0.9	0.1	0.0
Calm	0.0	0.0	0.8	0.2
Angry	1.0	0.0	0.0	0.0
Hungry	0.2	0.0	0.0	0.8

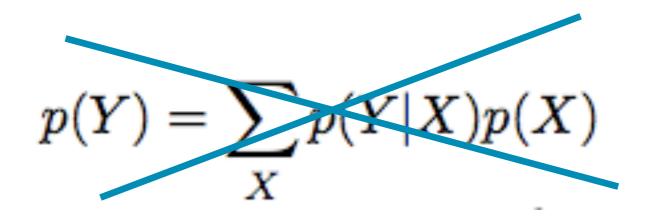
$P(zzz \text{ snort} | A, B, \Pi)$

= P (zzz| asleep) P(asleep) P(calm | asleep) P(snort|calm) + P(zzz| asleep) P(asleep) P(asleep) P(asleep) P(snort|asleep) = (0.9) (0.3) (0.2) (0.8) + (0.9) (0.3) (0.5) (0.1) = 0.0675 + 0.0135 = 0.081

You can see that this will grow increasingly difficult as the HMM grows increasingly larger (or there are fewer zeros in the transition matrix)

$$p(Y) = \sum_{X} p(Y|X)p(X)$$

Having to sum over every possible set of hidden states, in general, requires on the order of N^{T+1} multiplications, where T = # of time steps, and N = the number of states. The complexity is thus $O(N^T)$ Luckily, in order to calculate the most likely path we don't have to sum over all possible state sequences



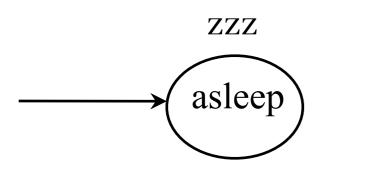
Because of the limited horizon property, the probability of the path at any one point only depends on the probability of the current point and the probability of the previous point An algorithm for efficiently calculating the probability of a sequence of observations

Incremental: at each observation step, you find the most likely path until that point

Complexity is O(N²T), assuming a fully connected model – a big improvement over O(N^T)

State transition matrix A:

	Asleep	Calm	Angry	Hungry
Asleep	0.5	0.2	0.1	0.2
Calm	0.4	0.3	0.1	0.2
Angry	0.1	0.2	0.6	0.1
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snort

Initial state probabilities Π :

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Output symbol matrix *B*:

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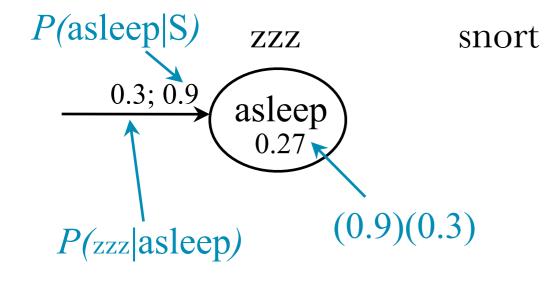
grumble

roar

There is only one state that outputs zzz

State transition matrix A:

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Asleep	0.5	0.2	0.1	0.2
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grumble

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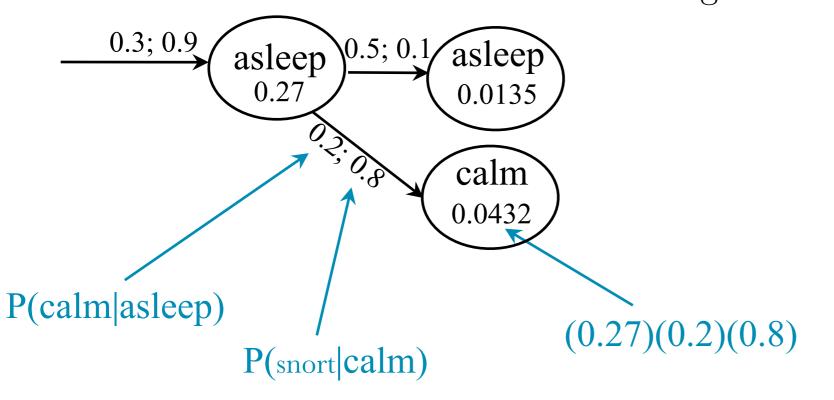
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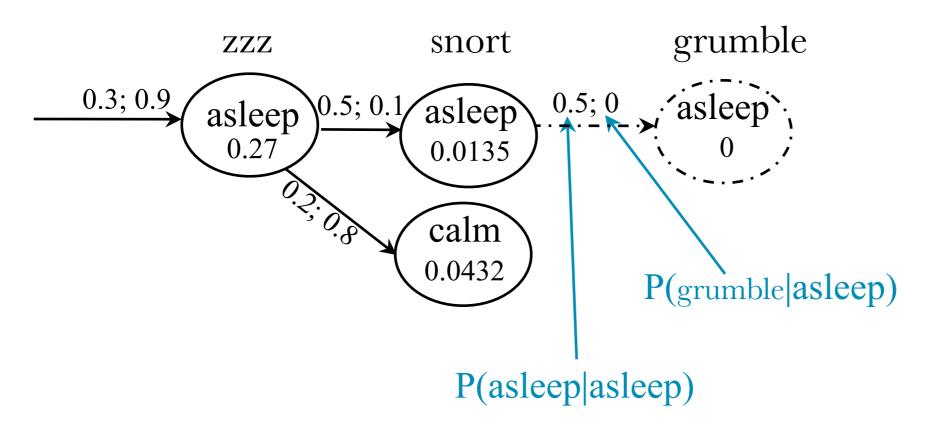
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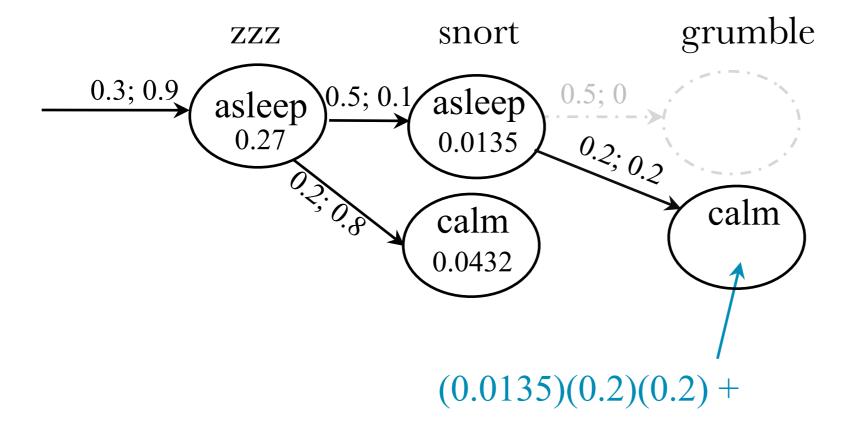
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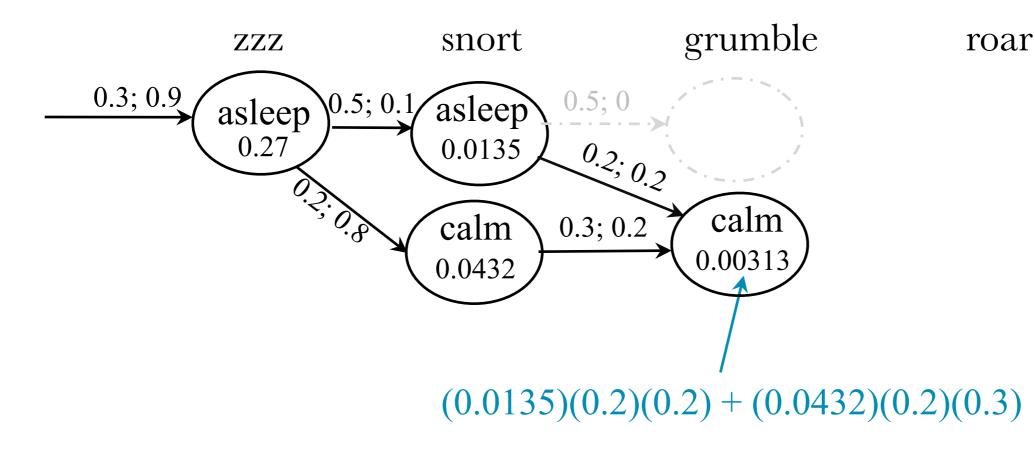
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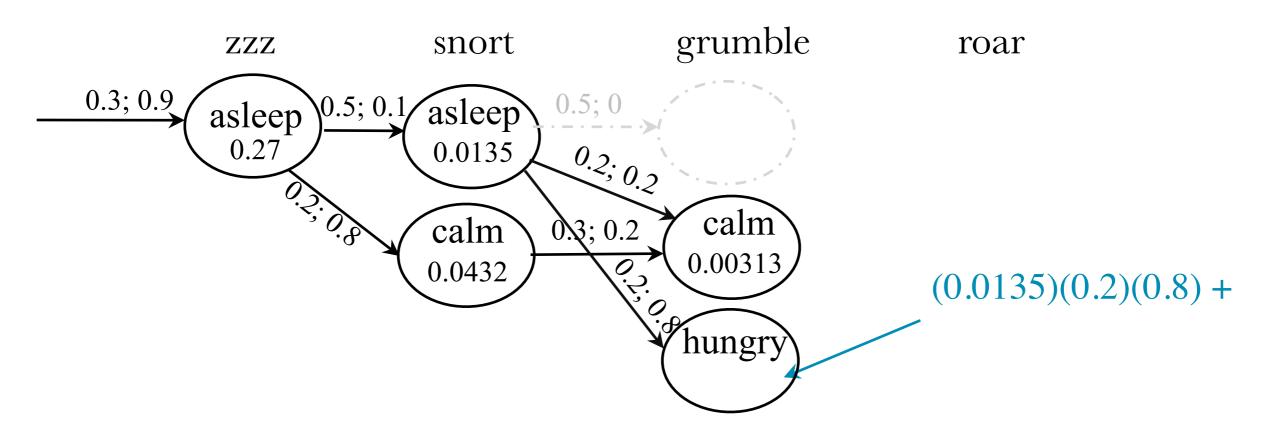
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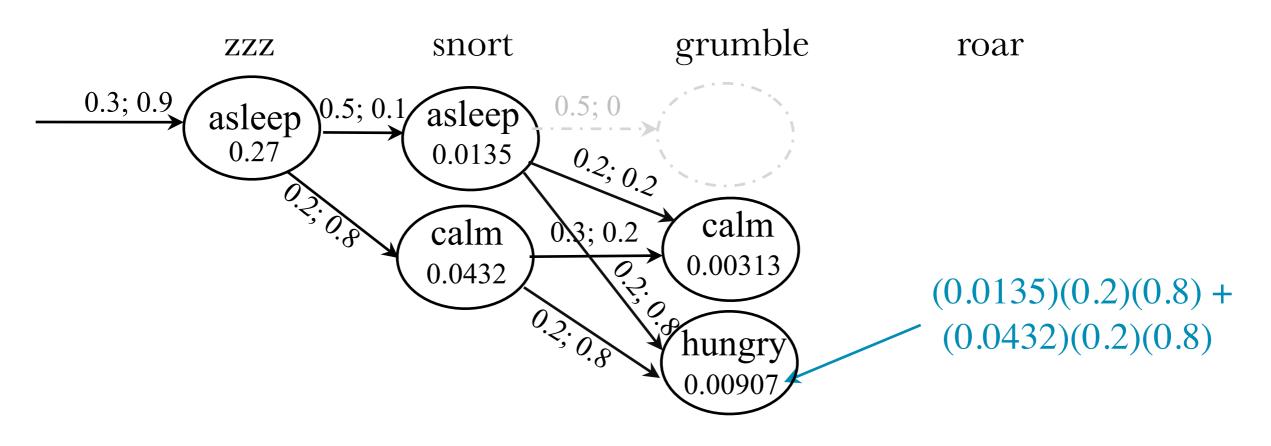
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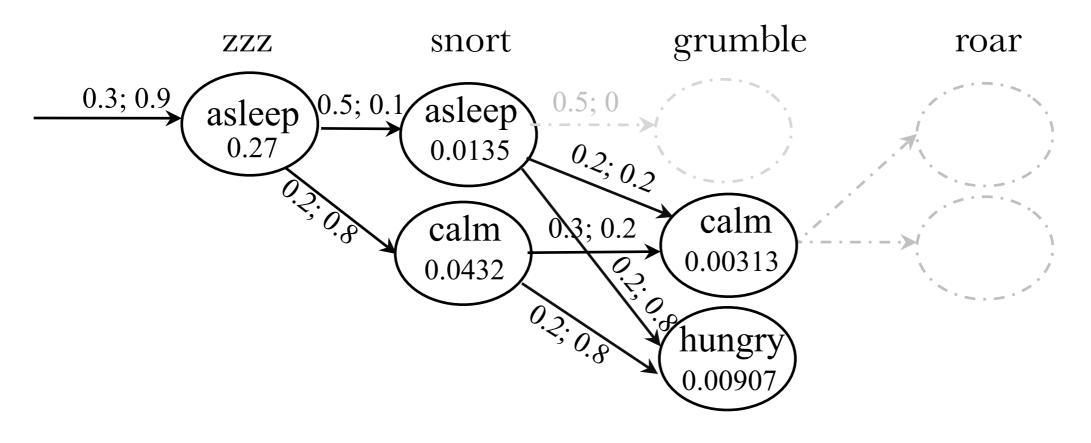
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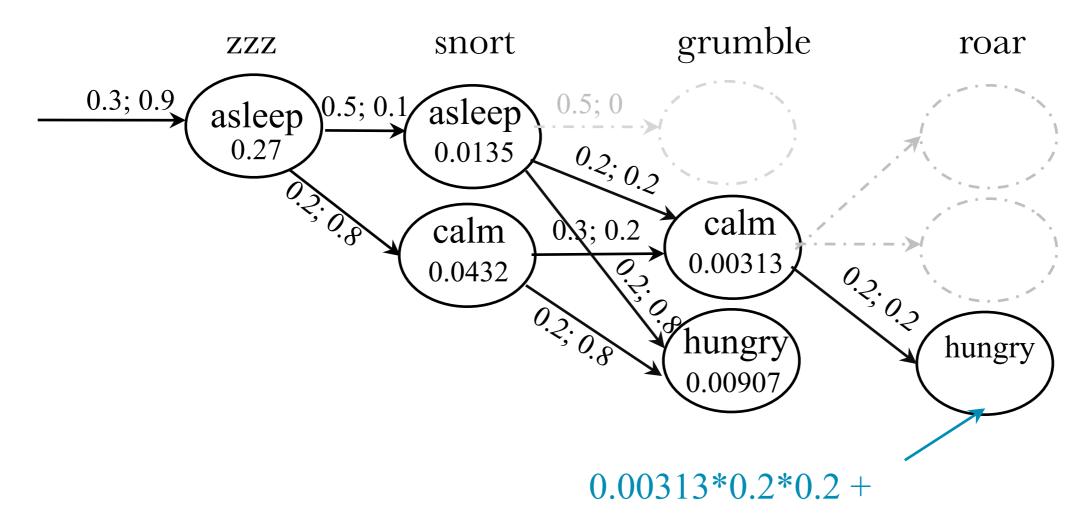
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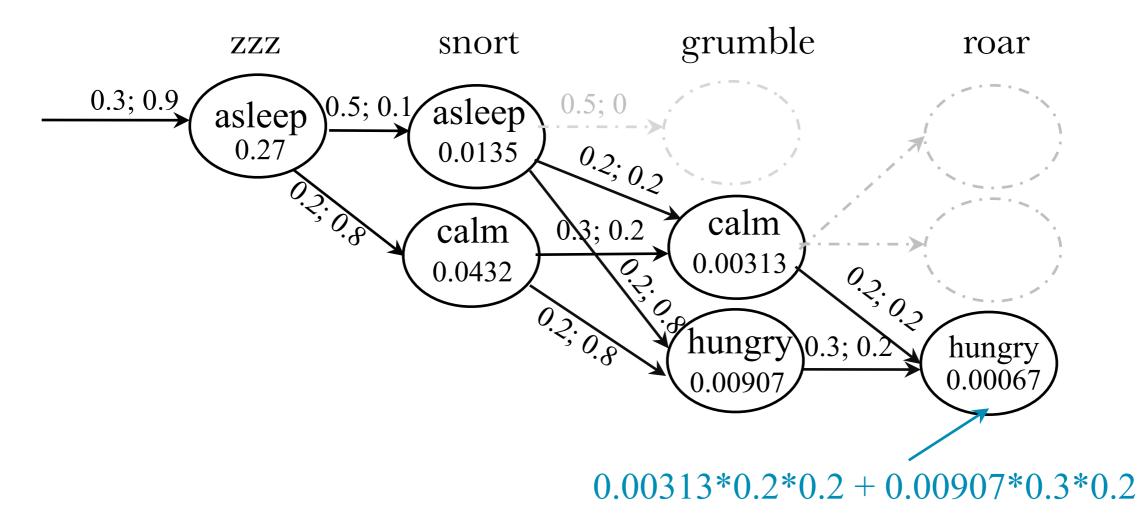
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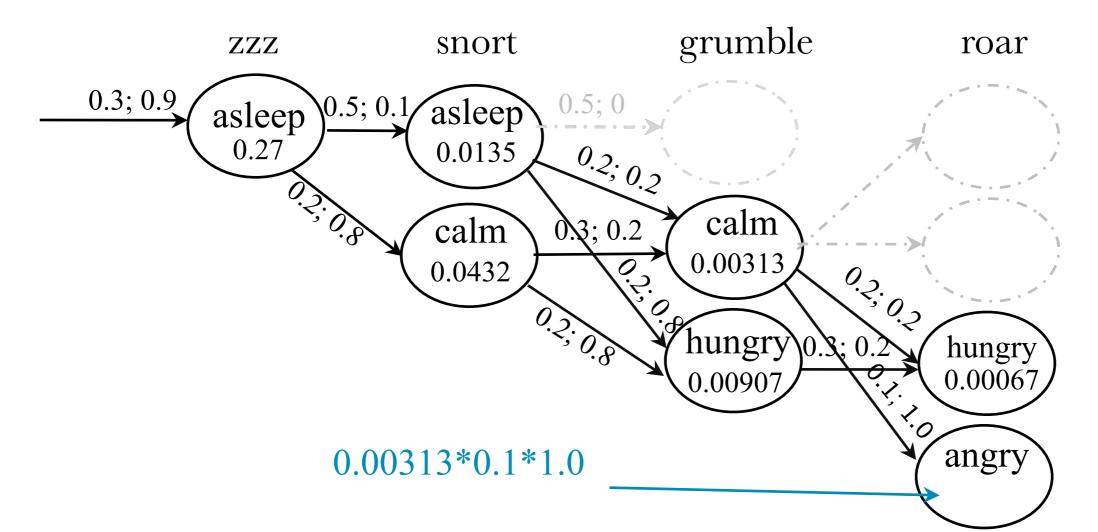
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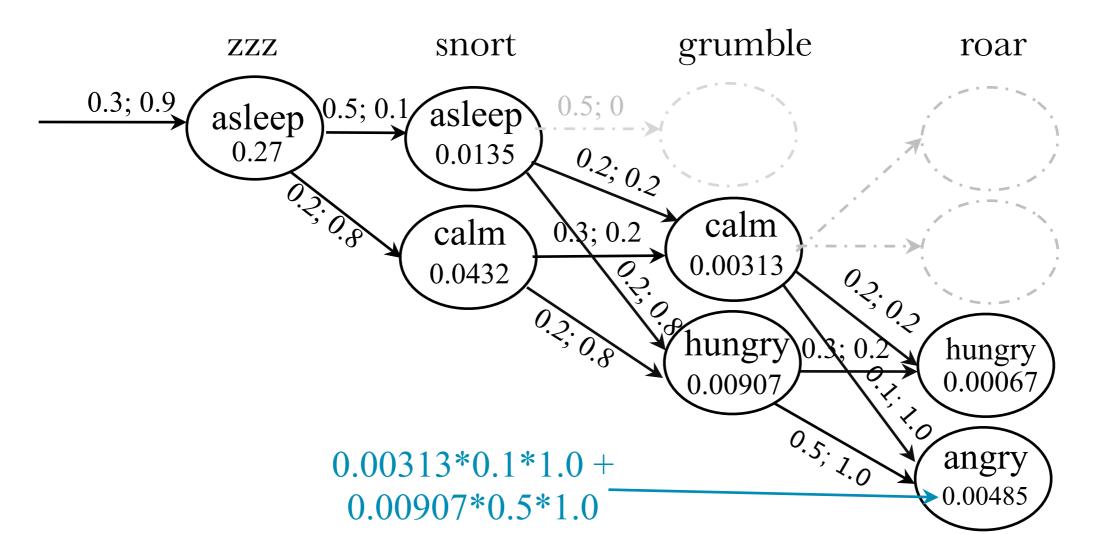
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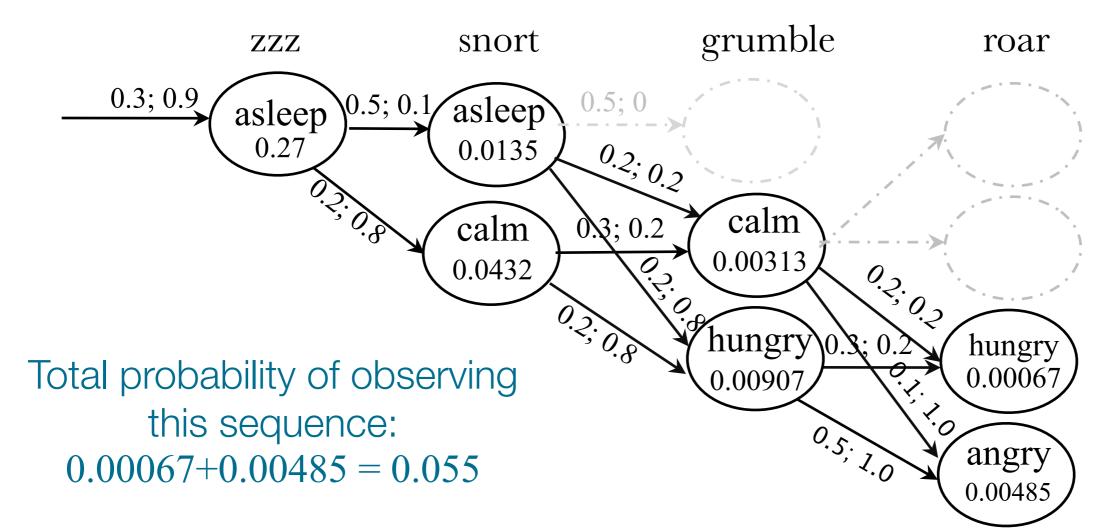
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ZZZ

snort

grumble

roar

This is called the **forward algorithm**, because we calculated incrementally moving forward in time

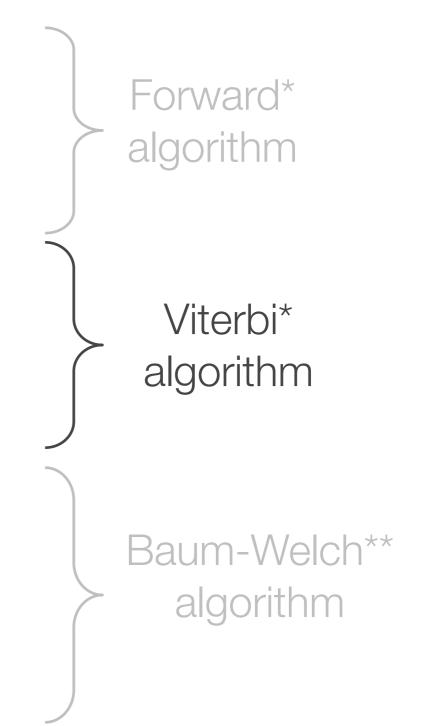
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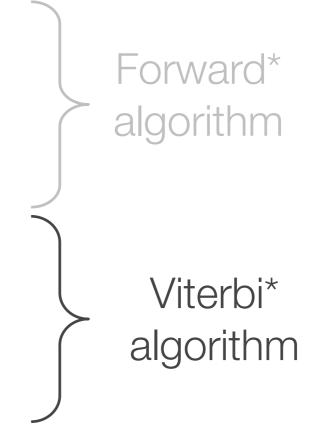
Three fundamental questions for HMMs

- Given a model M = (A, B, Π), how do we efficiently compute how likely a certain observation is?
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- Given a model M = (A, B, Π), how do we efficiently compute how likely a certain observation is?
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Idea: what if we maximise as we go through the trellis, rather than sum up all of the states?

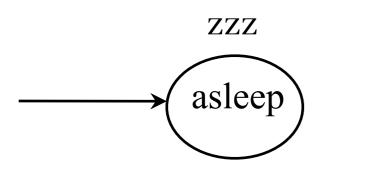
An algorithm for efficiently calculating the most likely path through an HMM, given a sequence of observations

Incremental: at each observation step, you find the most likely path until that point

Complexity is O(N²T), assuming a fully connected model – a big improvement over O(N^T)

State transition matrix A:

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snort

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Output symbol matrix *B*:

	Roar	Zzz	Snort	Grumble
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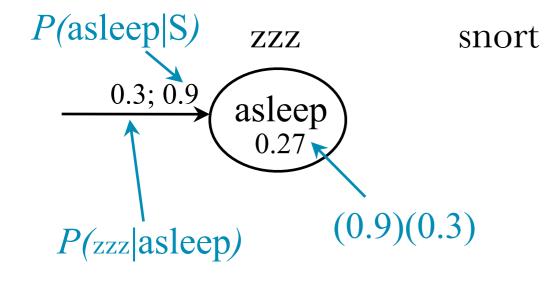
grumble

roar

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Calm	0.0	0.0	0.8	0.2
Angry	1.0	0.0	0.0	0.0
Hungry	0.2	0.0	0.0	0.8

grumble

roar

State transition matrix A:

	Asleep	Calm	Angry	Hungry
Asleep	0.5	0.2	0.1	0.2
Calm	0.4	0.3	0.1	0.2
Angry	0.1	0.2	0.6	0.1
Hungry	0.1	0.1	0.5	0.3

Initial state probabilities Π :

Asleep	Calm	Angry	Hungry
0.3	0.3	0.2	0.2

Output symbol matrix *B*:

	Roar	Zzz	Snort	Grumble
Asleep	0.0	0.9	0.1	0.0
Calm	0.0	0.0	0.8	0.2
Angry	1.0	0.0	0.0	0.0
Hungry	0.2	0.0	0.0	0.8

State transition matrix A:

	Asleep	Calm	Angry	Hungry
Asleep	0.5	0.2	0.1	0.2
Calm	0.4	0.3	0.1	0.2
Angry	0.1	0.2	0.6	0.1
Hungry	0.1	0.1	0.5	0.3

ZZZ

Initial state probabilities Π :

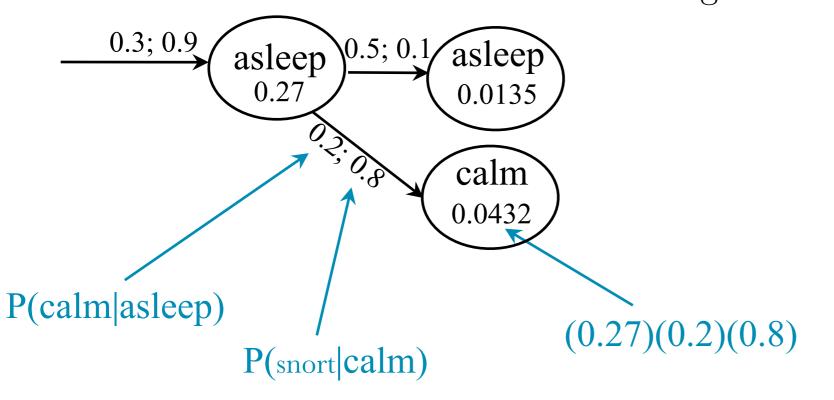
Asleep	Calm	Angry	Hungry
0.3	0.3	0.2	0.2

Output symbol matrix *B*:

	Roar	Zzz	Snort	Grumble
Asleep	0.0	0.9	0.1	0.0
Calm	0.0	0.0	0.8	0.2
Angry	1.0	0.0	0.0	0.0
Hungry	0.2	0.0	0.0	0.8

grumble

roar



snort

State transition matrix A:

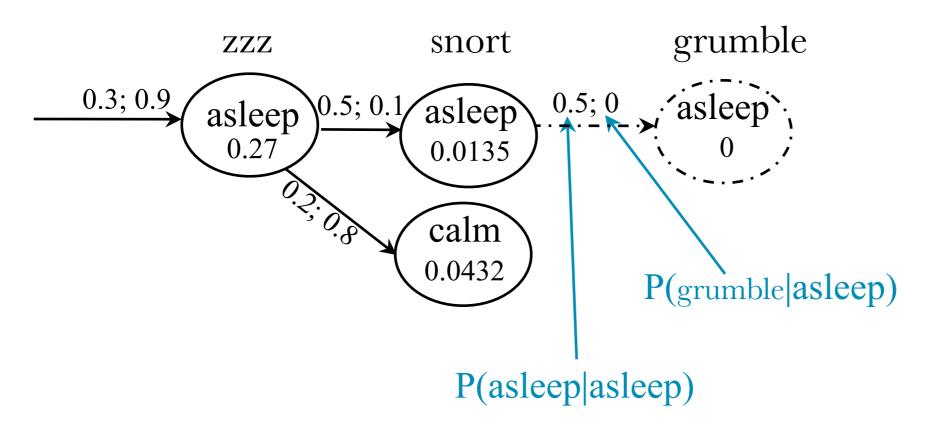
	Asleep	Calm	Angry	Hungry
Asleep	0.5	0.2	0.1	0.2
Calm	0.4	0.3	0.1	0.2
Angry	0.1	0.2	0.6	0.1
Hungry	0.1	0.1	0.5	0.3

Initial state probabilities Π :

Asleep	Calm	Angry	Hungry
0.3	0.3	0.2	0.2

Output symbol matrix B:

	Roar	Zzz	Snort	Grumble
Asleep	0.0	0.9	0.1	0.0
Calm	0.0	0.0	0.8	0.2
Angry	1.0	0.0	0.0	0.0
Hungry	0.2	0.0	0.0	0.8



State transition matrix A:

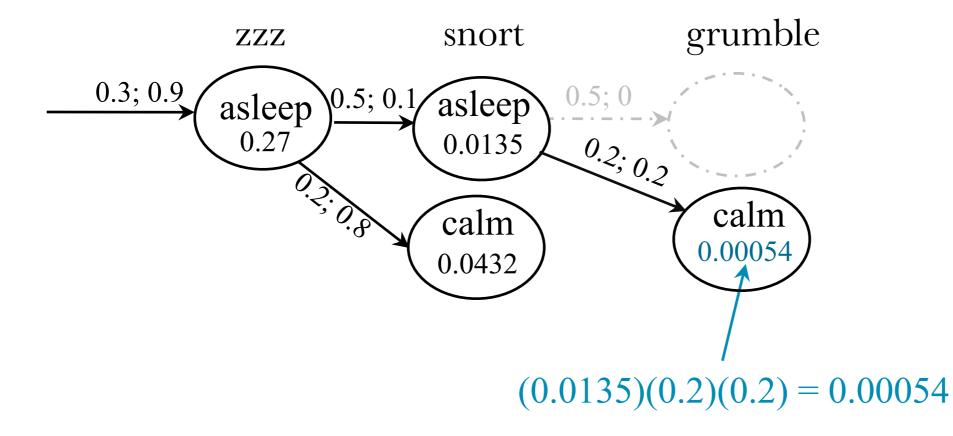
	Asleep	Calm	Angry	Hungry
Asleep	0.5	0.2	0.1	0.2
Calm	0.4	0.3	0.1	0.2
Angry	0.1	0.2	0.6	0.1
Hungry	0.1	0.1	0.5	0.3

Initial state probabilities Π :

Asleep	Calm	Angry	Hungry
0.3	0.3	0.2	0.2

Output symbol matrix B:

	Roar	Zzz	Snort	Grumble
Asleep	0.0	0.9	0.1	0.0
Calm	0.0	0.0	0.8	0.2
Angry	1.0	0.0	0.0	0.0
Hungry	0.2	0.0	0.0	0.8



State transition matrix A:

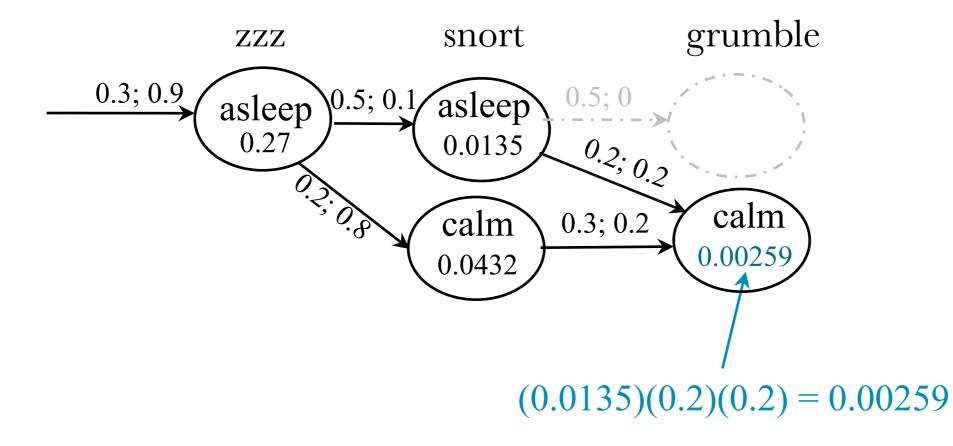
	Asleep	Calm	Angry	Hungry
Asleep	0.5	0.2	0.1	0.2
Calm	0.4	0.3	0.1	0.2
Angry	0.1	0.2	0.6	0.1
Hungry	0.1	0.1	0.5	0.3

Initial state probabilities Π :

Asleep	Calm	Angry	Hungry
0.3	0.3	0.2	0.2

Output symbol matrix B:

	Roar	Zzz	Snort	Grumble
Asleep	0.0	0.9	0.1	0.0
Calm	0.0	0.0	0.8	0.2
Angry	1.0	0.0	0.0	0.0
Hungry	0.2	0.0	0.0	0.8



State transition matrix A:

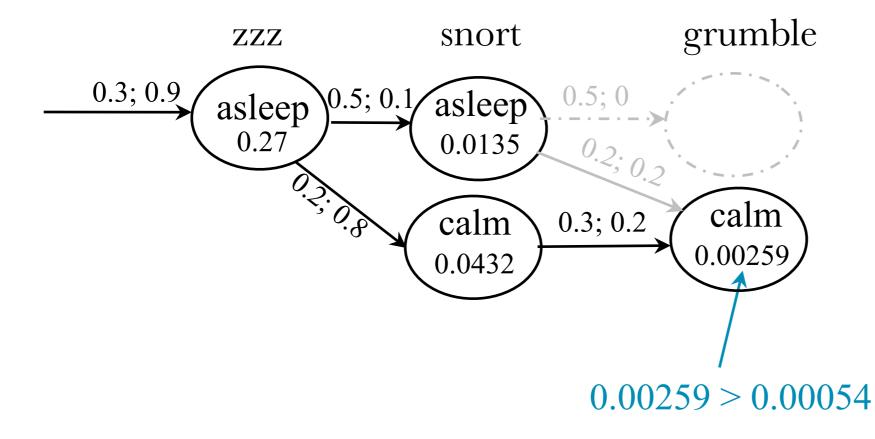
	Asleep	Calm	Angry	Hungry
Asleep	0.5	0.2	0.1	0.2
Calm	0.4	0.3	0.1	0.2
Angry	0.1	0.2	0.6	0.1
Hungry	0.1	0.1	0.5	0.3

Initial state probabilities Π :

Asleep	Calm	Angry	Hungry
0.3	0.3	0.2	0.2

Output symbol matrix B:

	Roar	Zzz	Snort	Grumble
Asleep	0.0	0.9	0.1	0.0
Calm	0.0	0.0	0.8	0.2
Angry	1.0	0.0	0.0	0.0
Hungry	0.2	0.0	0.0	0.8



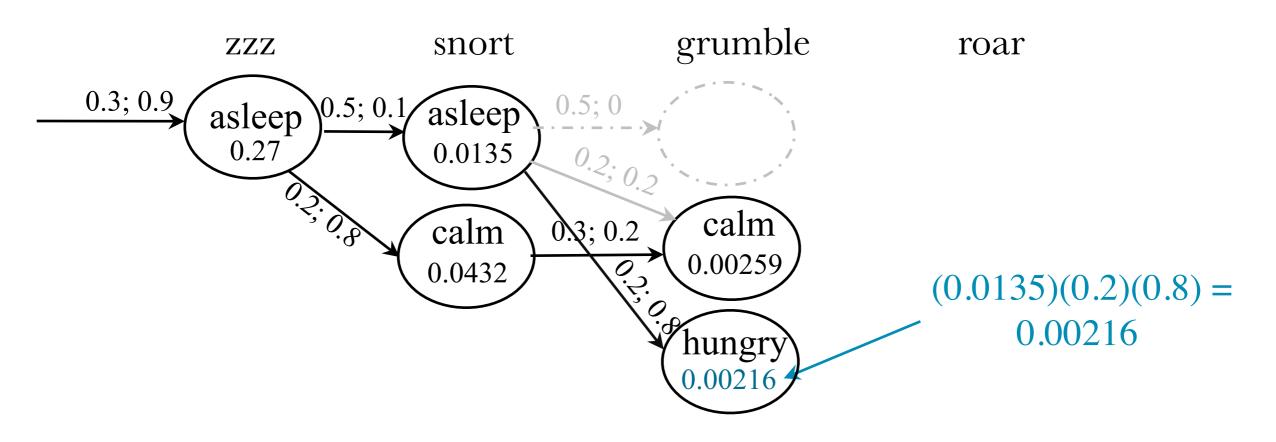
State transition matrix A:

	Asleep	Calm	Angry	Hungry
Asleep	0.5	0.2	0.1	0.2
Calm	0.4	0.3	0.1	0.2
Angry	0.1	0.2	0.6	0.1
Hungry	0.1	0.1	0.5	0.3

Initial state probabilities Π :

Asleep	Calm	Angry	Hungry
0.3	0.3	0.2	0.2

	Roar	Zzz	Snort	Grumble
Asleep	0.0	0.9	0.1	0.0
Calm	0.0	0.0	0.8	0.2
Angry	1.0	0.0	0.0	0.0
Hungry	0.2	0.0	0.0	0.8



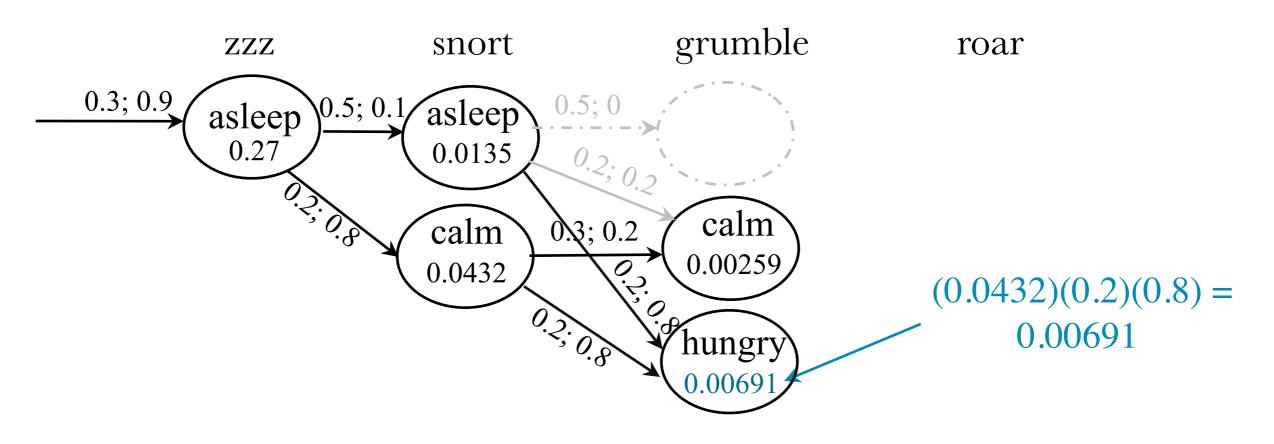
State transition matrix A:

	Asleep	Calm	Angry	Hungry
Asleep	0.5	0.2	0.1	0.2
Calm	0.4	0.3	0.1	0.2
Angry	0.1	0.2	0.6	0.1
Hungry	0.1	0.1	0.5	0.3

Initial state probabilities Π :

Asleep	Calm	Angry	Hungry
0.3	0.3	0.2	0.2

	Roar	Zzz	Snort	Grumble
Asleep	0.0	0.9	0.1	0.0
Calm	0.0	0.0	0.8	0.2
Angry	1.0	0.0	0.0	0.0
Hungry	0.2	0.0	0.0	0.8



State transition matrix *A*:

	Asleep	Calm	Angry	Hungry
Asleep	0.5	0.2	0.1	0.2
Calm	0.4	0.3	0.1	0.2
Angry	0.1	0.2	0.6	0.1
Hungry	0.1	0.1	0.5	0.3

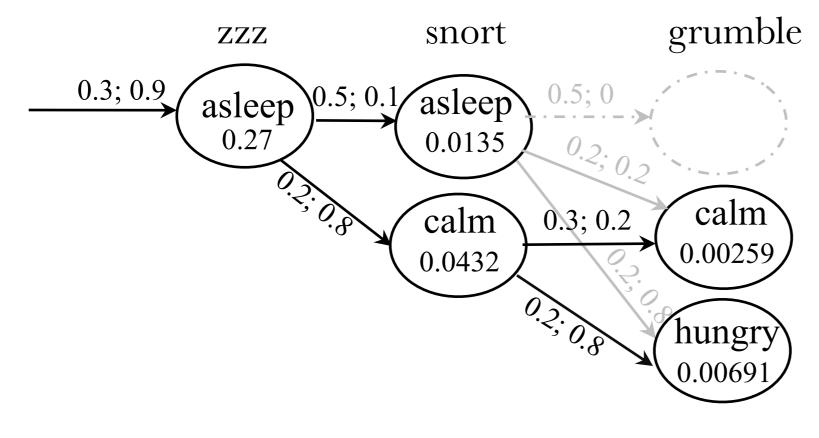
Initial state probabilities Π :

Asleep	Calm	Angry	Hungry
0.3	0.3	0.2	0.2

Output symbol matrix B:

	Roar	Zzz	Snort	Grumble
Asleep	0.0	0.9	0.1	0.0
Calm	0.0	0.0	0.8	0.2
Angry	1.0	0.0	0.0	0.0
Hungry	0.2	0.0	0.0	0.8

roar



0.00691 > 0.00216

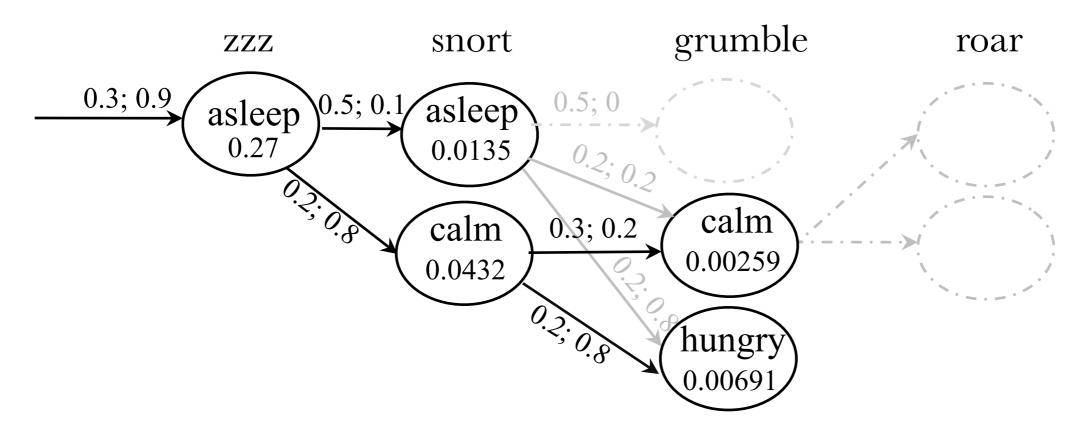
State transition matrix A:

	Asleep	Calm	Angry	Hungry
Asleep	0.5	0.2	0.1	0.2
Calm	0.4	0.3	0.1	0.2
Angry	0.1	0.2	0.6	0.1
Hungry	0.1	0.1	0.5	0.3

Initial state probabilities Π :

Asleep	Calm	Angry	Hungry
0.3	0.3	0.2	0.2

	Roar	Zzz	Snort	Grumble
Asleep	0.0	0.9	0.1	0.0
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Angry	1.0	0.0	0.0	0.0
Hungry	0.2	0.0	0.0	0.8



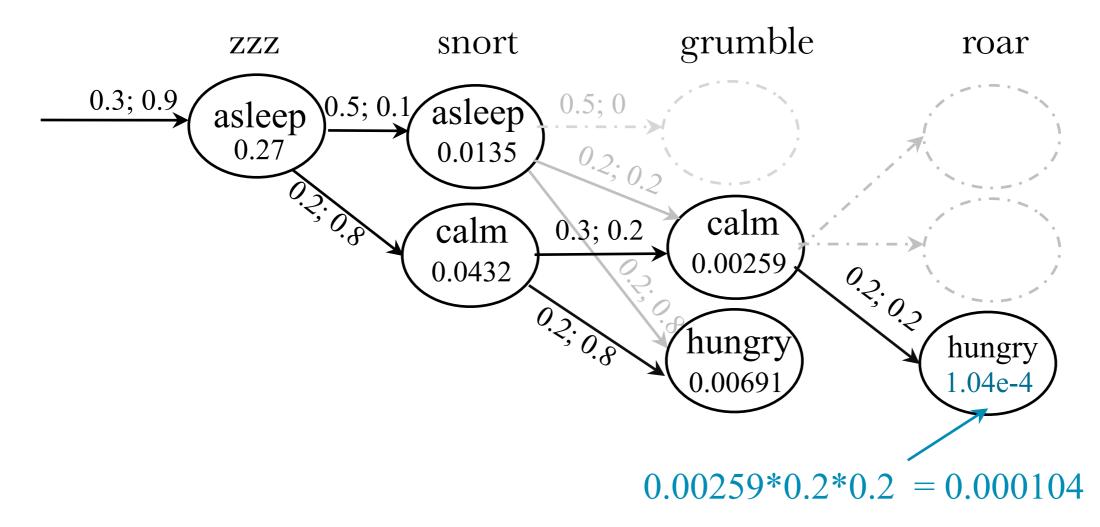
State transition matrix A:

	Asleep	Calm	Angry	Hungry
Asleep	0.5	0.2	0.1	0.2
Calm	0.4	0.3	0.1	0.2
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Hungry	0.2	0.0	0.0	0.8



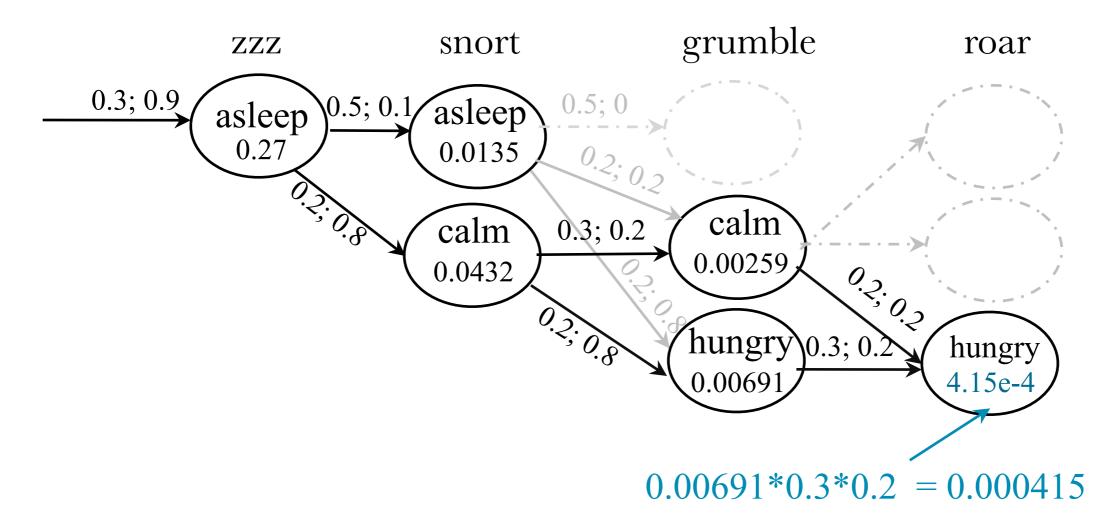
State transition matrix A:

	Asleep	Calm	Angry	Hungry
Asleep	0.5	0.2	0.1	0.2
Calm	0.4	0.3	0.1	0.2
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Asleep	Calm	Angry	Hungry
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	Roar	Zzz	Snort	Grumble
Asleep	0.0	0.9	0.1	0.0
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Angry	1.0	0.0	0.0	0.0
Hungry	0.2	0.0	0.0	0.8



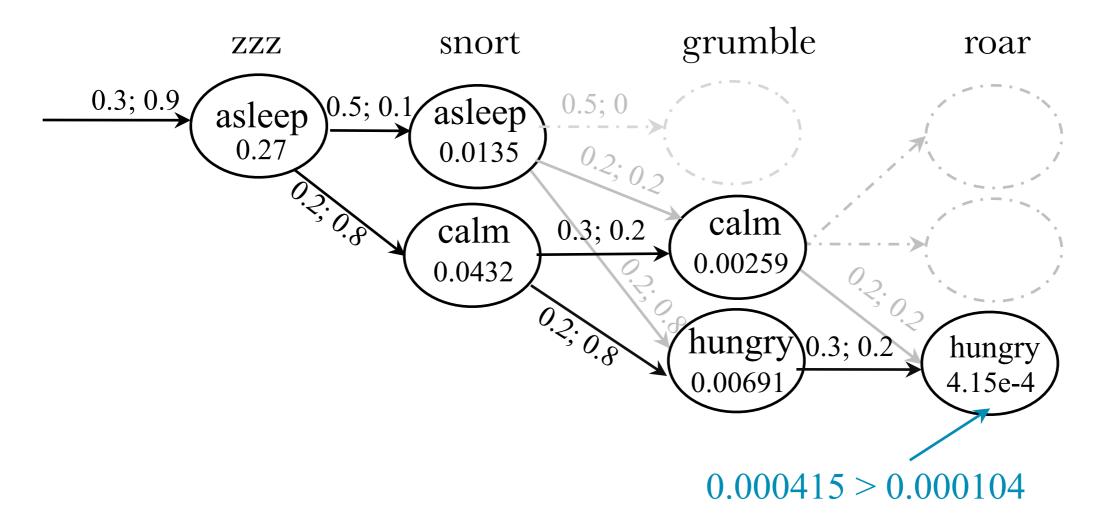
State transition matrix A:

	Asleep	Calm	Angry	Hungry
Asleep	0.5	0.2	0.1	0.2
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	Roar	Zzz	Snort	Grumble
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Angry	1.0	0.0	0.0	0.0
Hungry	0.2	0.0	0.0	0.8



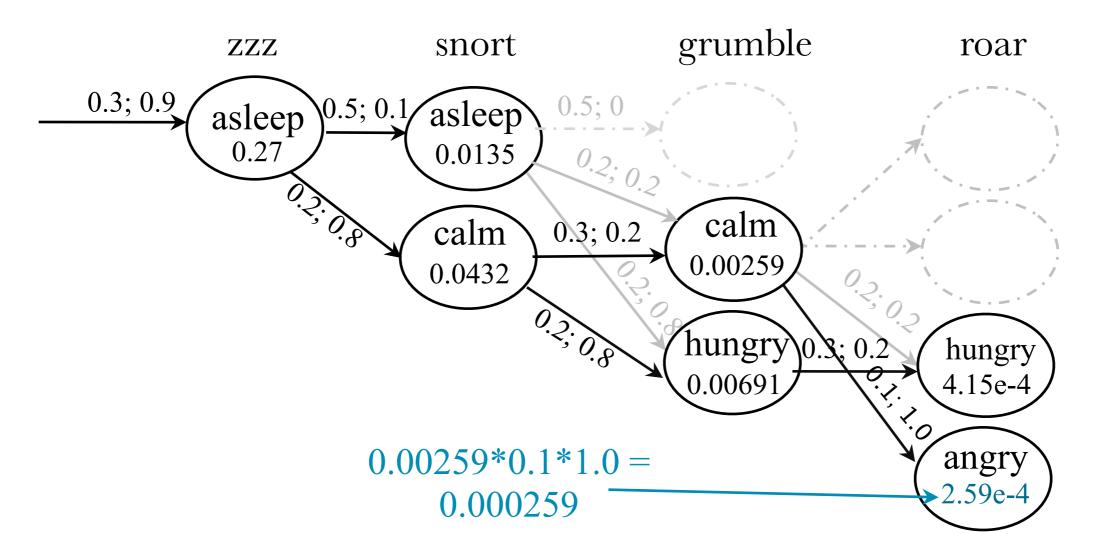
State transition matrix A:

	Asleep	Calm	Angry	Hungry
Asleep	0.5	0.2	0.1	0.2
Calm	0.4	0.3	0.1	0.2
Angry	0.1	0.2	0.6	0.1
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Initial state probabilities Π :

Asleep	Calm	Angry	Hungry
0.3	0.3	0.2	0.2

	Roar	Zzz	Snort	Grumble
Asleep	0.0	0.9	0.1	0.0
Calm	0.0	0.0	0.8	0.2
Angry	1.0	0.0	0.0	0.0
Hungry	0.2	0.0	0.0	0.8



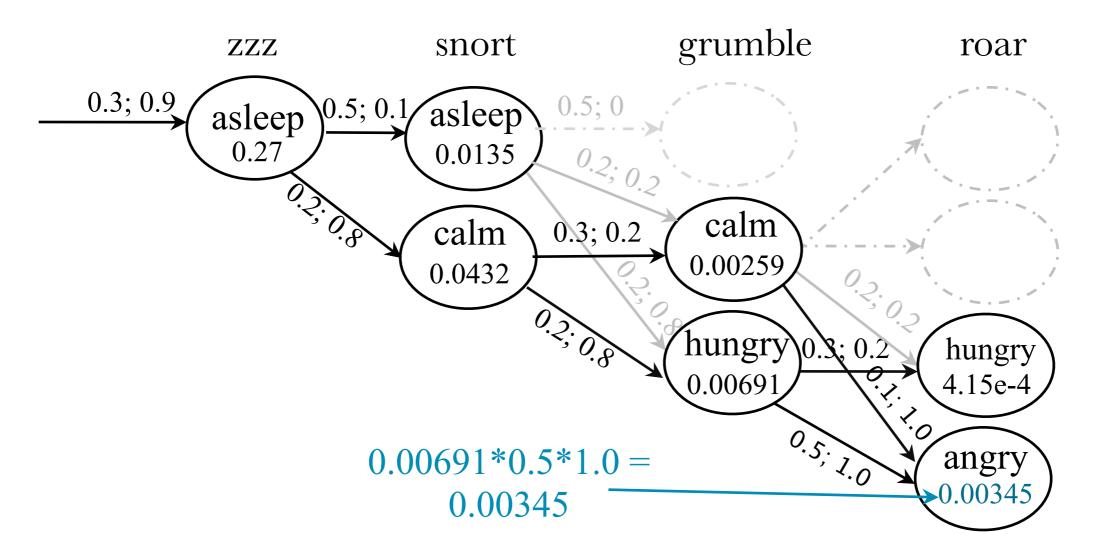
State transition matrix A:

	Asleep	Calm	Angry	Hungry
Asleep	0.5	0.2	0.1	0.2
Calm	0.4	0.3	0.1	0.2
Angry	0.1	0.2	0.6	0.1
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Initial state probabilities Π :

Asleep	Calm	Angry	Hungry
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	Roar	Zzz	Snort	Grumble
Asleep	0.0	0.9	0.1	0.0
Calm	0.0	0.0	0.8	0.2
Angry	1.0	0.0	0.0	0.0
Hungry	0.2	0.0	0.0	0.8



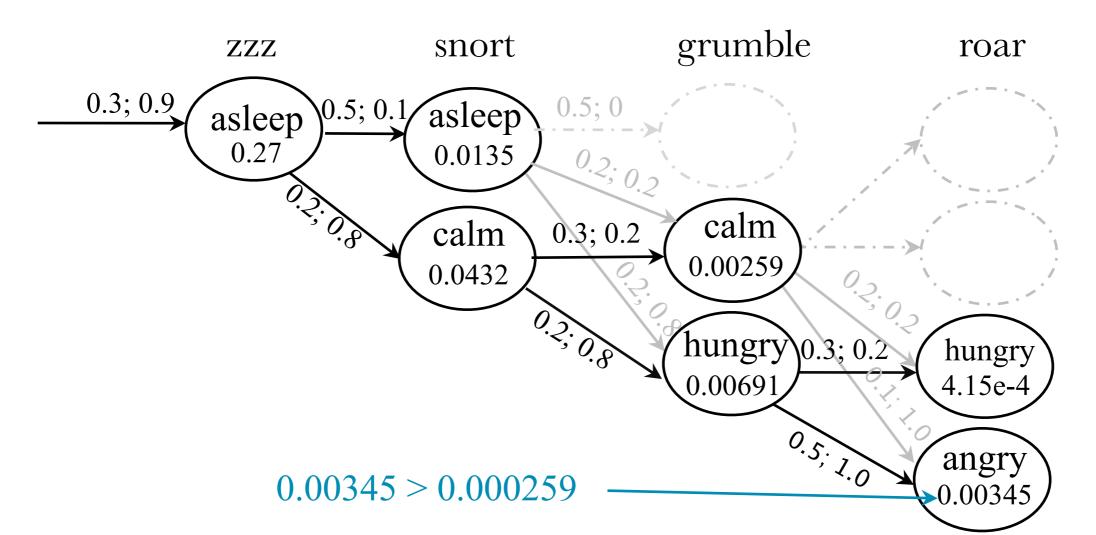
State transition matrix A:

	Asleep	Calm	Angry	Hungry
Asleep	0.5	0.2	0.1	0.2
Calm	0.4	0.3	0.1	0.2
Angry	0.1	0.2	0.6	0.1
Hungry	0.1	0.1	0.5	0.3

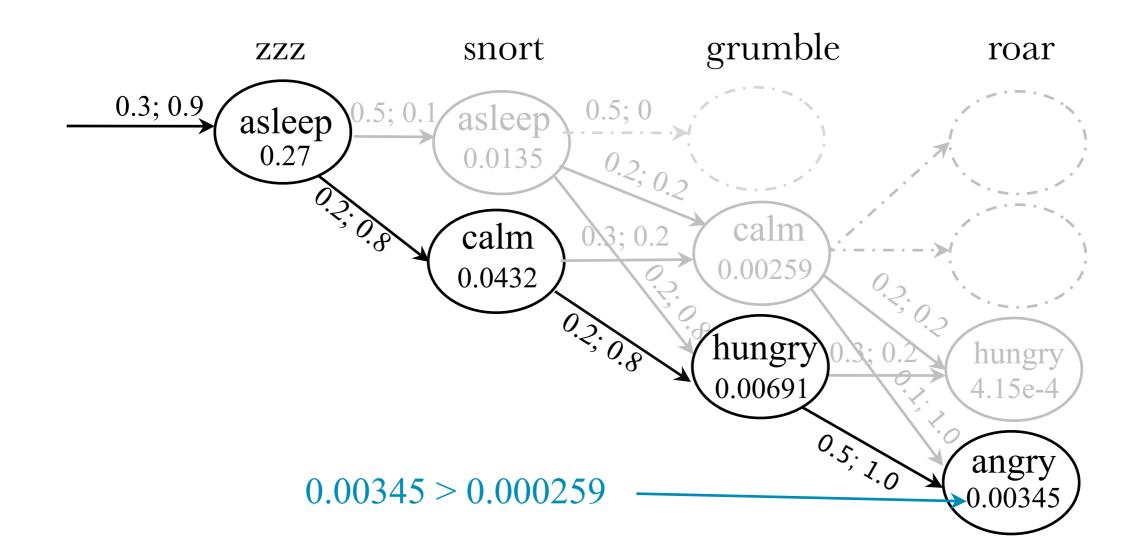
Initial state probabilities Π :

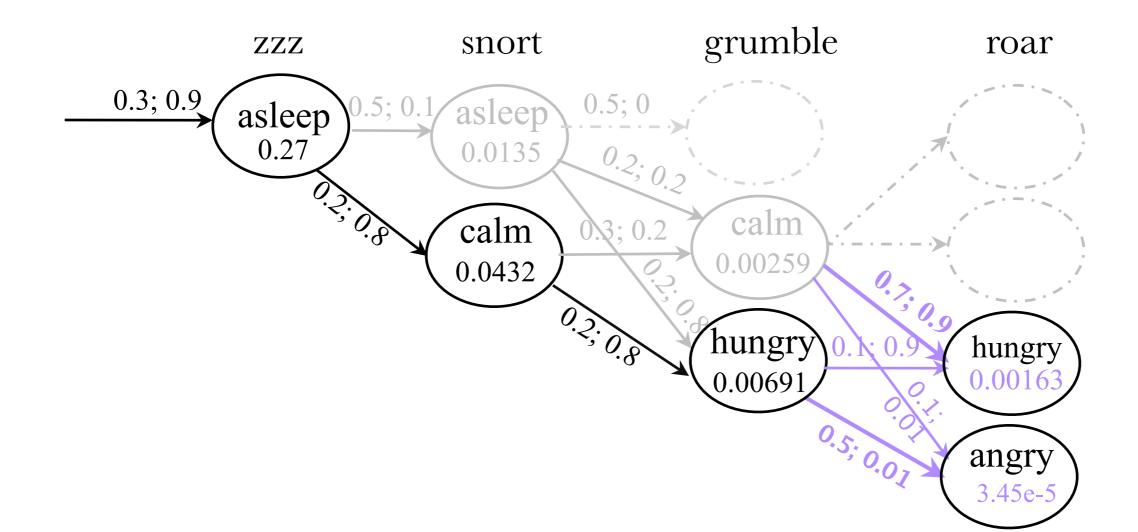
Asleep	Calm	Angry	Hungry
0.3	0.3	0.2	0.2

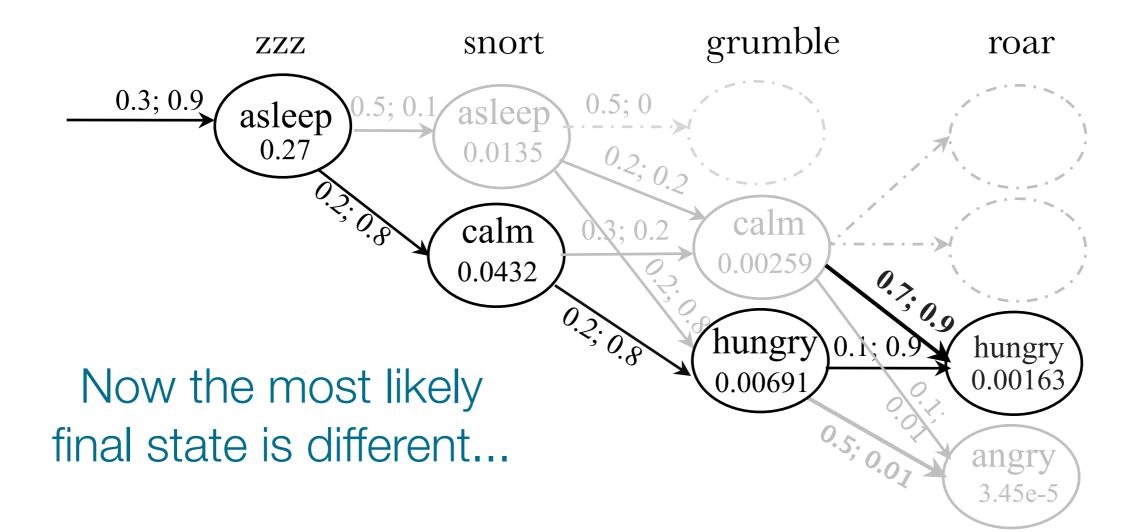
	Roar	Zzz	Snort	Grumble
Asleep	0.0	0.9	0.1	0.0
Calm	0.0	0.0	0.8	0.2
Angry	1.0	0.0	0.0	0.0
Hungry	0.2	0.0	0.0	0.8

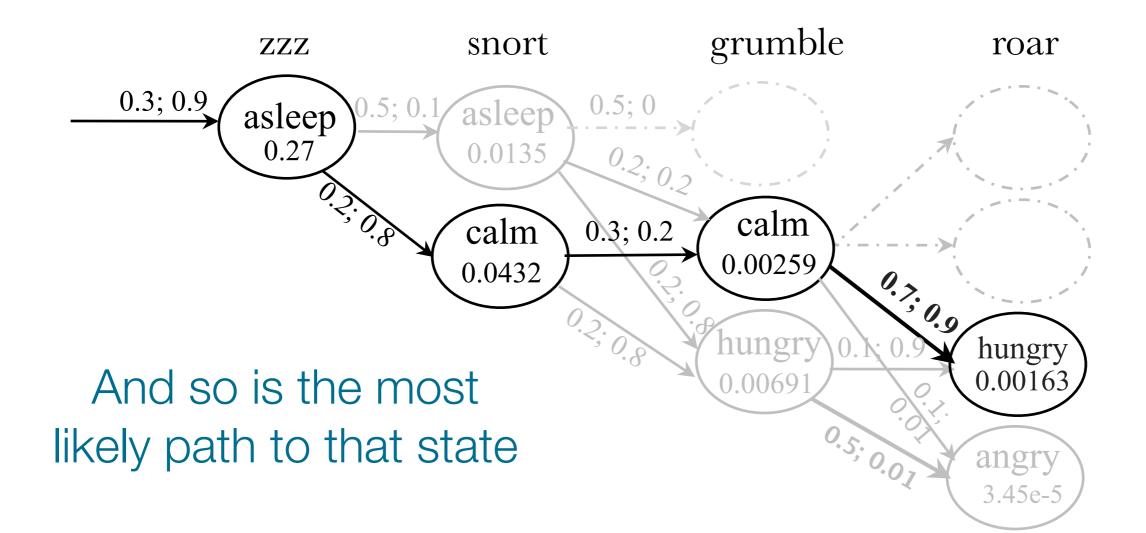


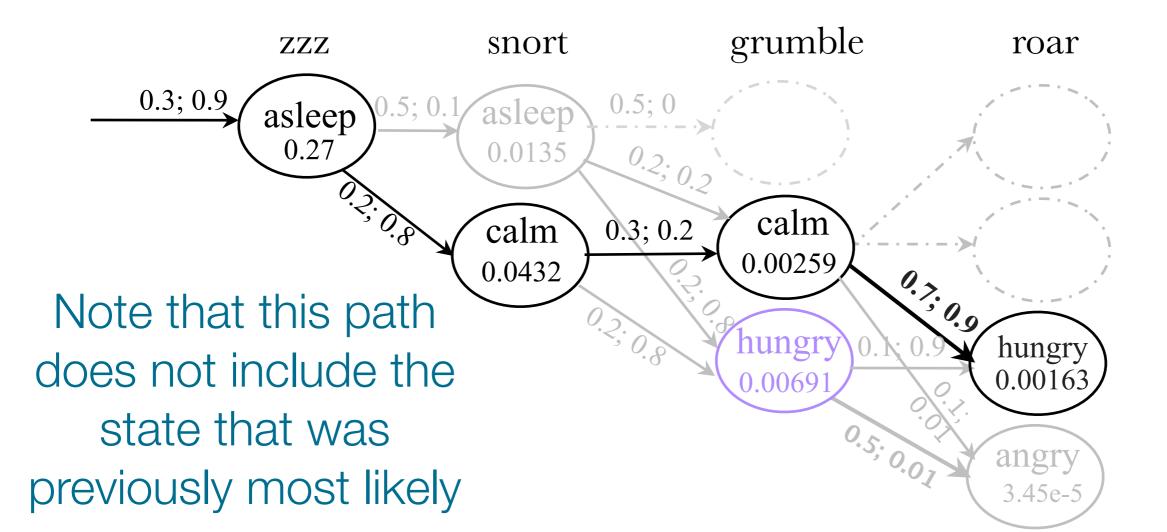
This worked out...









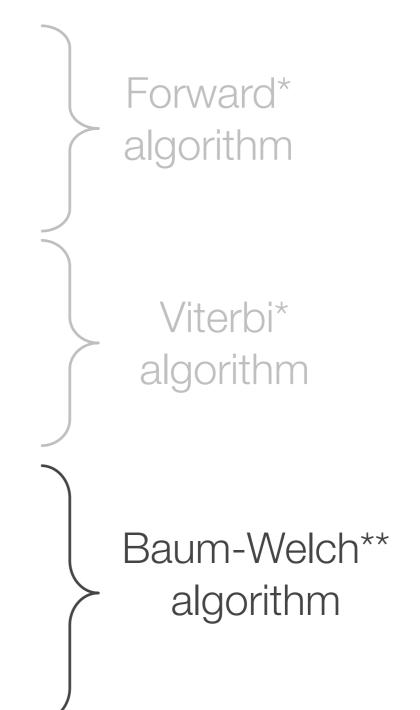


In order to calculate the most likely state sequence, you need to find the maximum transition at each point, get to the end, and then **backtrack** through

This algorithm – finding all of the forward probabilities (maxima, not sums), and then backtracking – is called the Viterbi algorithm.

Three fundamental questions for HMMs

- Given a model M = (A, B, Π), how do we efficiently compute how likely a certain observation is?
- Given a sequence of observations *Y* and a model *M*, how do we infer the state sequence that best explains the observations?
- Given an observation sequence Y and a space of possible models found by varying the model parameters M = (A,B,Π) , how do we find the model that best explains the observed data?



I'll give the main idea of how it works, but not all of the nitty-gritty detail. You don't need to be able to implement this – I just want to get you started in case you ever want to.

Given an observation sequence Y and a space of possible models found by varying the model parameters M = (A,B,Π) , how do we find the model that best explains the observed data?

Baum-Welch** algorithm

Basic idea: This is just an EM algorithm! But instead of:

Assignment step (E-step):

Calculate the likelihood of each data point in each cluster, assuming the cluster is a Gaussian with the current mean, standard deviation, and weight

Update step (M-step):

Recalculate the means

Recalculate the standard deviations

Recalculate the weights

$$r_k^{(n)} = \frac{w_k \frac{1}{\prod_{i=1}^{I} \sqrt{2\pi}\sigma_i^{(k)}} \exp\left(-\sum_{i=1}^{I} (m_i^{(k)} - x_i^{(n)})^2 / 2(\sigma_i^{(k)})^2\right)}{\sum_{k'} w_{k'} \frac{1}{\prod_{i=1}^{I} \sqrt{2\pi}\sigma_i^{(k')}} \exp\left(-\sum_{i=1}^{I} (m_i^{(k')} - x_i^{(n)})^2 / 2(\sigma_i^{(k')})^2\right)}$$

$$\mathbf{m}^{(k)} = \frac{\sum_{k} r_{k}^{(n)} \mathbf{x}^{(n)}}{\sum_{n} r_{k}^{(n)}}$$

$$\sigma_{k}^{2} = \frac{\sum_{n} r_{k}^{(n)} (x_{i}^{(n)} - m_{i}^{(k)})^{2}}{\sum_{n} r_{k}^{(n)}}$$

$$w_{k} = \frac{\sum_{n} r_{k}^{(n)}}{\sum_{k} \sum_{n} r_{k}^{(n)}}$$

Basic idea: This is just an EM algorithm! But instead of:

Assignment step (E-step):

Calculate the probability of the observation sequence given the current model (A, B, Π)

Update step (M-step):

Recalculate ARecalculate BRecalculate Π

 $a_{ij} = \text{expected number of transitions from state } i \text{ to } j$ Expected number of transitions from state i

 $b_{ijk} =$ expected # of transitions from state *i* to *j* with *k* observed Expected number of transitions from *i* to *j*

 π_i = expected frequency in state *i* at time *t*=1

Forward algorithm Because it is an EM algorithm, it has the same properties:

1. Guaranteed (fairly rapid) convergence, but only to local maxima, not global maxima

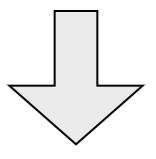
2. Dependence on initial values. In practice, it is especially important to have good starting points for the output parameters B; estimates of A are fairly robust to initial starting point.

We have defined what a Hidden Markov Model (HMM) is, and proposed it as a better model for language than an n-gram model (i.e., a standard Markov Model)

We have seen in detail how it is possible to calculate the most probable path of hidden states in an HMM, and the probability of an observation

We have seen in brief how it is possible to figure out (imperfectly) what the most probable set of transition probabilities (A,B,Π) are, given a set of observations

We have defined what a Hidden Markov Model (HMM) is, and proposed it as a better model for language than an n-gram model (i.e., a standard Markov Model)

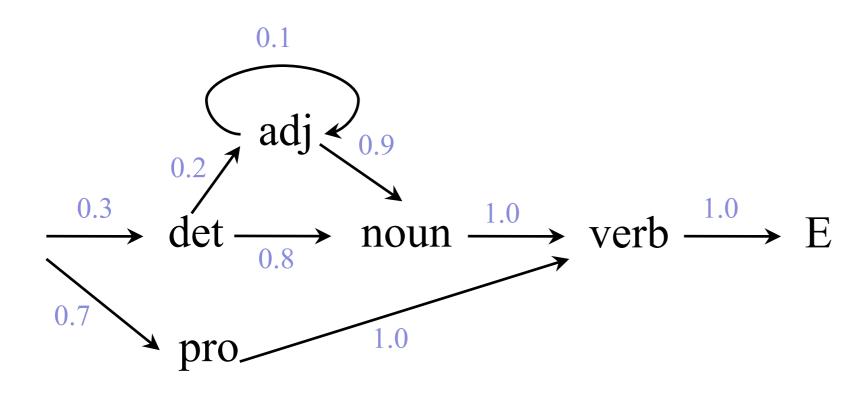


But are HMMs indeed a good model of language?

Not really.

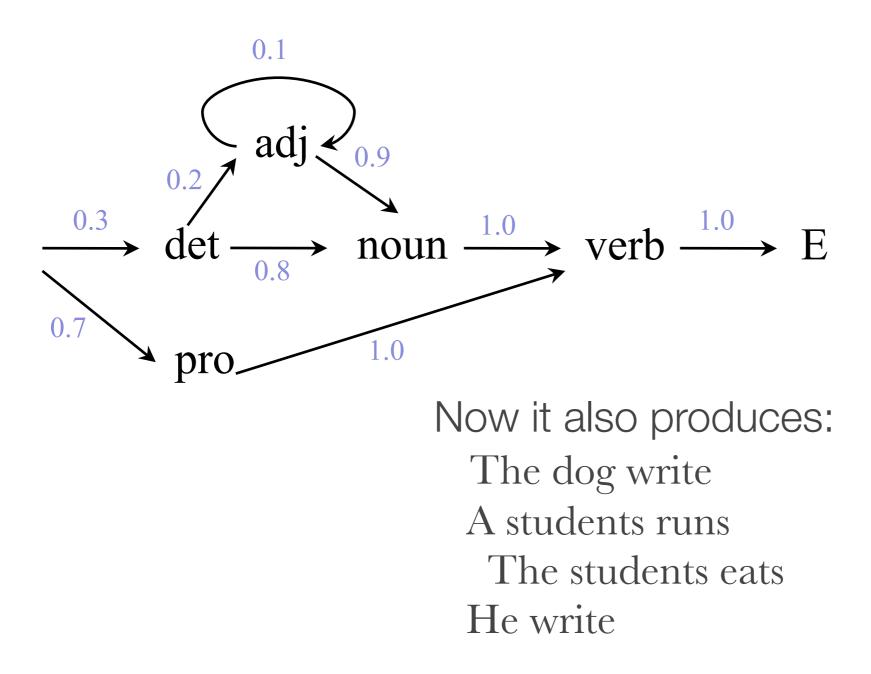
Plan

- Last time: introduction to HMMs
 - Limitations of n-grams applied to language
 - Basics of HMMs
- ➡ Today: finishing HMMs, and more complex structures
 - Determining the likelihood of a given observation
 - Calculating the most likely state sequence
 - Finding the best HMM for given data
 - More complex models of language



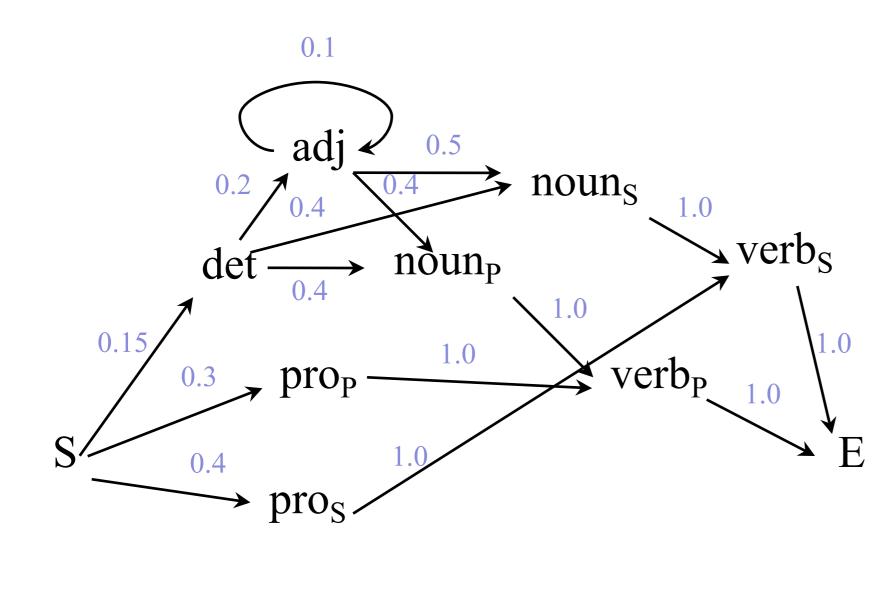
- (0.5) verb \rightarrow eats
- (0.5) verb \rightarrow runs
- (0.3) pro \rightarrow he
- (0.3) pro \rightarrow she
- (0.4) pro \rightarrow it
- (0.7) det \rightarrow the
- (0.3) det \rightarrow a
- (0.4) noun \rightarrow boy
- (0.4) noun \rightarrow dog
- (0.2) noun \rightarrow tiger
- (1.0) adj \rightarrow happy

Suppose you want to make it able to produce: The students write



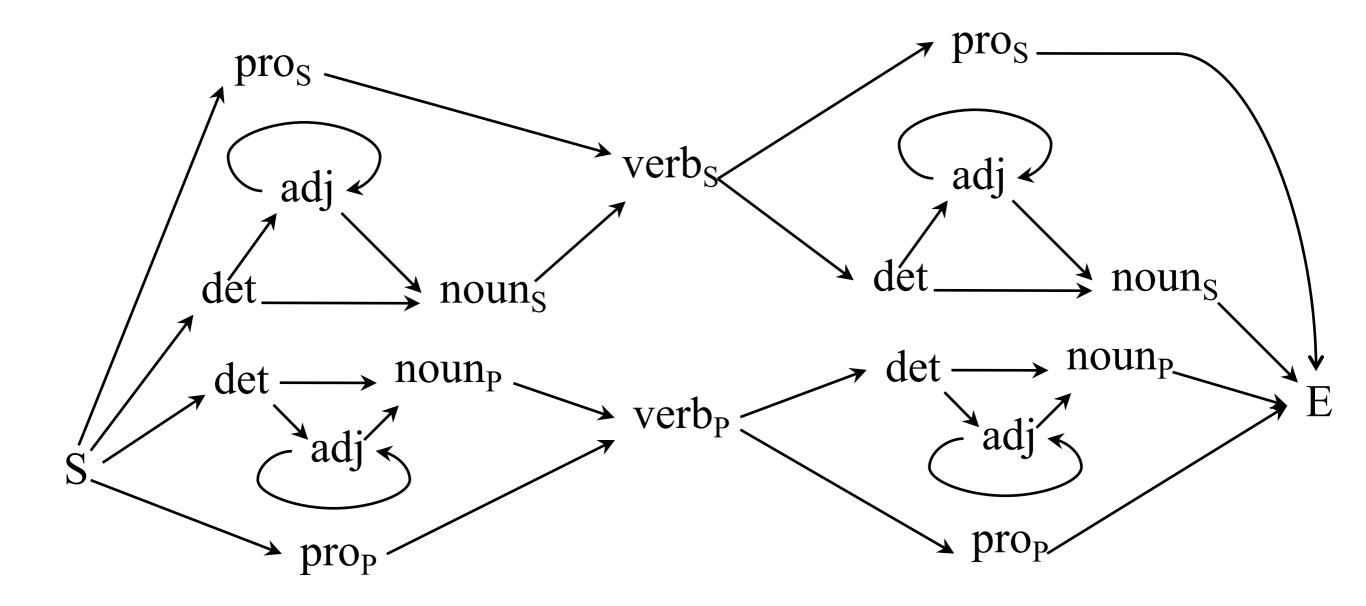
(0.5) verb \rightarrow eats (0.3) verb \rightarrow runs (0.2) verb \rightarrow write (0.3) pro \rightarrow he (0.3) pro \rightarrow she (0.4) pro \rightarrow it (0.7) det \rightarrow the (0.3) det \rightarrow a (0.4) noun \rightarrow boy (0.2) noun \rightarrow dog (0.2) noun \rightarrow tiger (0.2) noun \rightarrow students (1.0) adj \rightarrow happy

As before, you have to add new states to the model to solve this problem

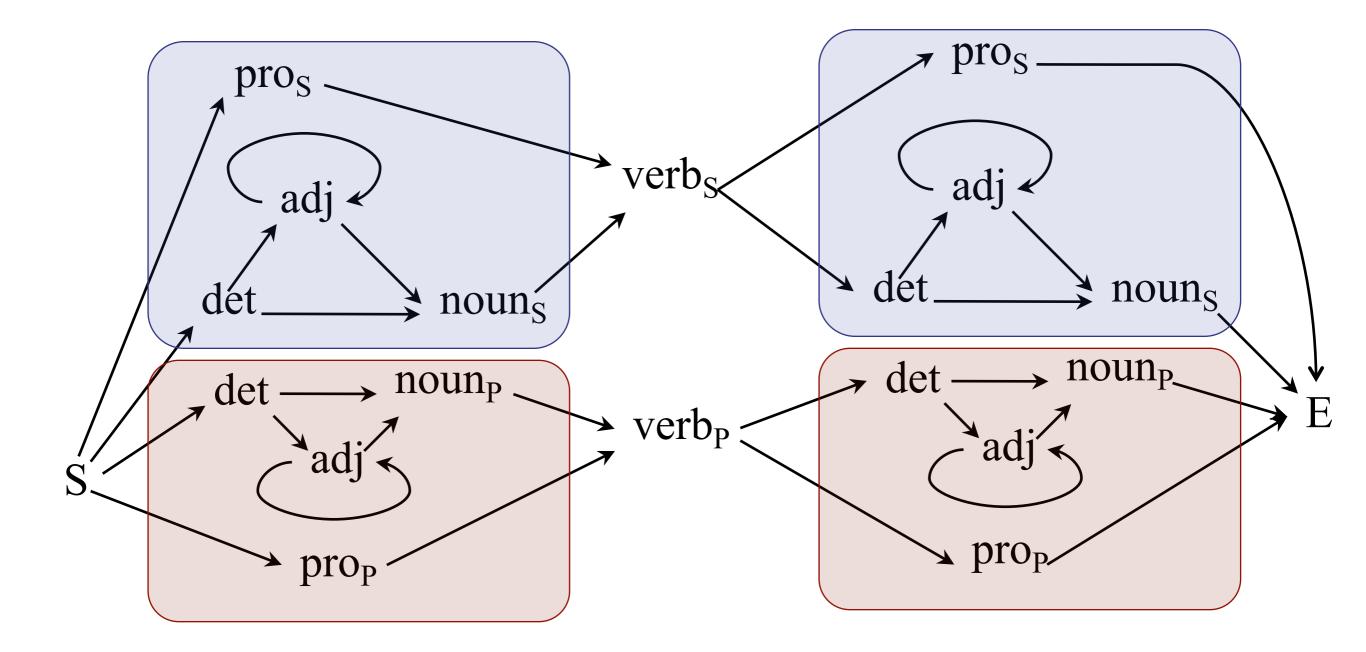


(0.5) verb_s \rightarrow eats (0.5) verb_s \rightarrow runs (1.0) verb_P \rightarrow write (0.3) pro_s \rightarrow he (0.3) pro_s \rightarrow she (0.4) pro_s \rightarrow it (0.7) det \rightarrow the (0.3) det \rightarrow a (0.4) noun_s \rightarrow boy (0.4) noun_s \rightarrow dog (0.2) noun_s \rightarrow tiger (1.0) noun_P \rightarrow students (1.0) adj \rightarrow happy

It's made worse if we make the grammar even more complicated

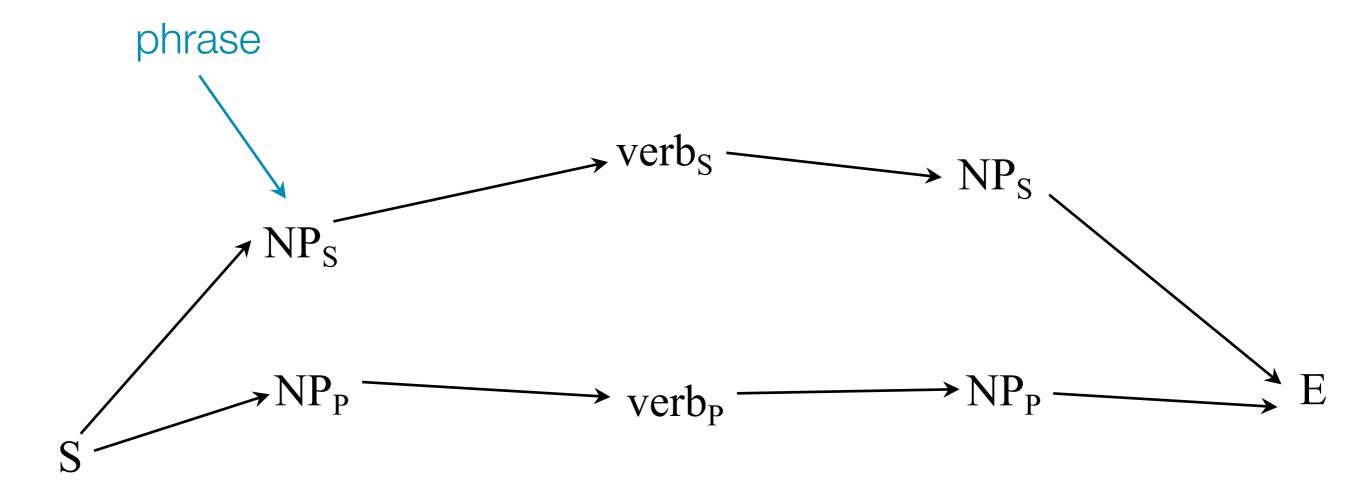


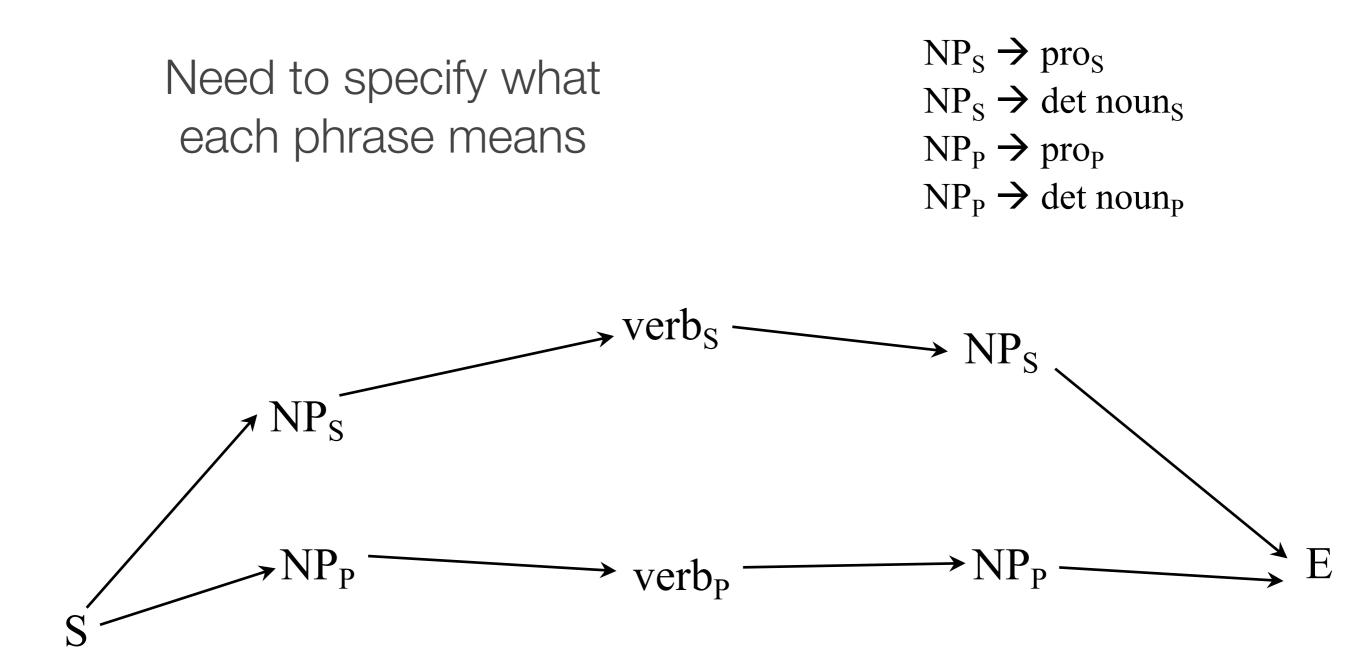
However, you might notice a regularity in this grammar



Still have a parameter explosion problem

However, you might notice a regularity in this grammar

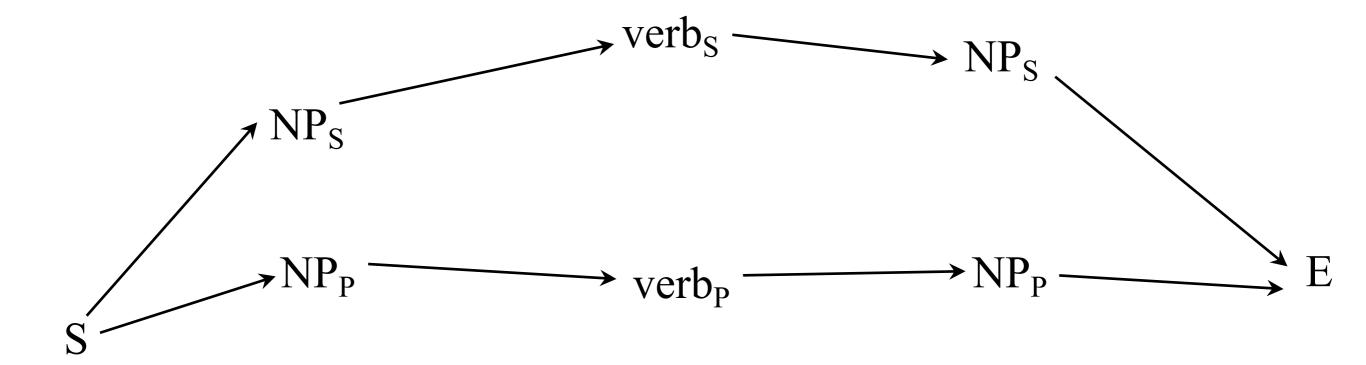


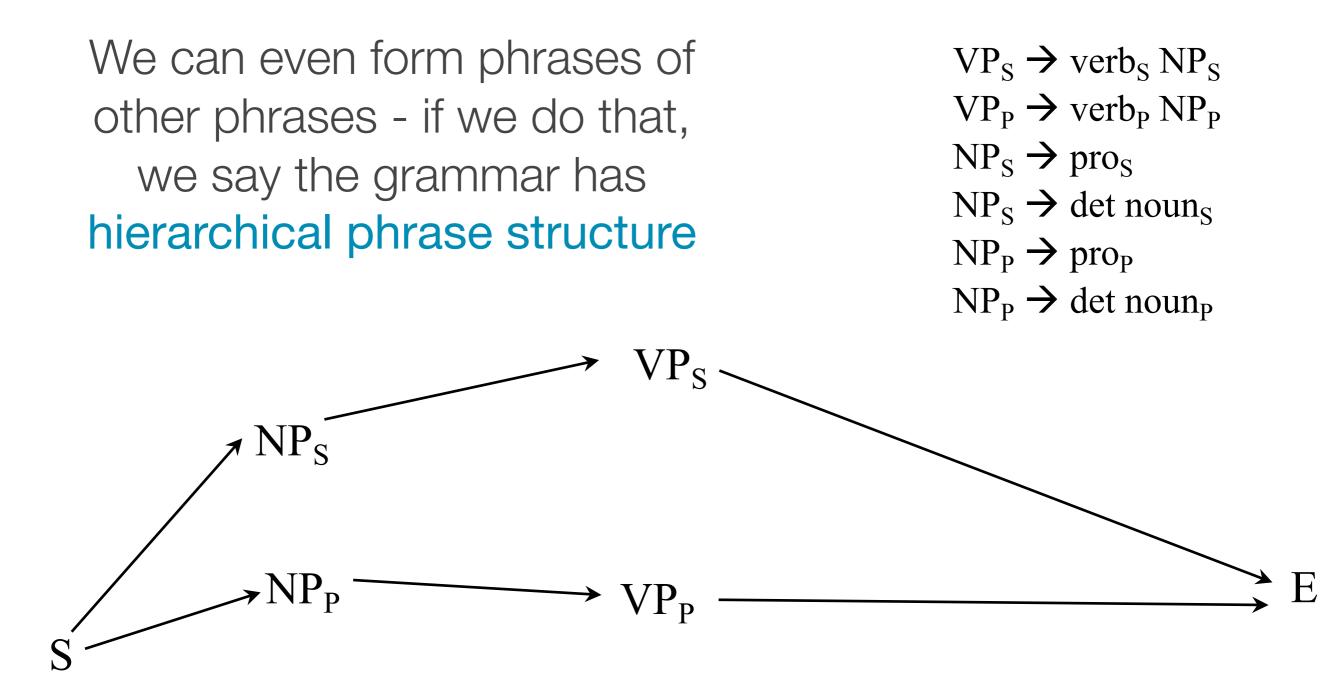


Still have a parameter explosion problem

A grammar like this, which is formed by "clustering" states of an HMM, has phrase structure

 $NP_{S} \rightarrow pro_{S}$ $NP_{S} \rightarrow det noun_{S}$ $NP_{P} \rightarrow pro_{P}$ $NP_{P} \rightarrow det noun_{P}$





Context-free grammars can be formed from an HMM by clustering states into phrases. They have hierarchical phrase structure: a key feature of language

- $S \rightarrow NP_S VP_S$
- $S \rightarrow NP_P VP_P$
- $VP_S \rightarrow verb_S NP_S$
- $VP_P \rightarrow verb_P NP_P$
- $NP_S \rightarrow pro_S$
- $NP_S \rightarrow det noun_S$
- $NP_P \rightarrow pro_P$
- $NP_P \rightarrow det noun_P$

Formal definition of CFG (or PCFG)

A PCFG G with a vocabulary V and n nonterminals consists of:

- A set of terminals, $\{w^k\}, k = 1, ..., V$ {a, the, boy, tiger, dog, school, it, she, her, him, he...}
- A set of nonterminals, $\{N^i\}, i = 1, ..., n$ $\{S, VP_S, VP_P, NP_S, NP_P, PRO_S, D, N_S, PRO_P, N_P, V_S, A, V_P\}$
 - A designated start symbol, N^1
 - A set of rules, $\{N^i \to \zeta^j\}$, where ζ^j is a sequence of terminals and nonterminals
 - A corresponding set of probabilities on rules such that $\forall i \sum_{j} P(N^i \to \zeta^j) = 1$ (0.3) $N_S \to boy$ (0.3) $N_S \to tiger$ (0.3) $N_S \to tiger$

S

		(0.3) N _S \rightarrow dog
	(0.3) $PRO_S \rightarrow he$	(0.2) $N_P \rightarrow boy$
	(0.3) $PRO_S \rightarrow she$	(0.2) $N_P \rightarrow tiger$
$(0.5) S \rightarrow NP_S VP_S$	(0.4) $\text{PRO}_{\text{S}} \rightarrow \text{it}$	(0.2) $N_P \rightarrow dog$
$(0.5) \mathbf{S} \rightarrow \mathbf{NP}_{\mathbf{P}} \mathbf{VP}_{\mathbf{P}}$	(0.3) $PRO_P \rightarrow her$	(0.15) N _P \rightarrow school
$(1.0) \operatorname{VP}_{S} \operatorname{V}_{S} \operatorname{NP}_{S}$	(0.3) $PRO_P \rightarrow him$	(0.15) N _P \rightarrow house
$(1.0) \operatorname{VP}_{\operatorname{P}} \operatorname{V}_{\operatorname{P}} \operatorname{NP}_{\operatorname{P}}$	(0.4) $\text{PRO}_{\text{P}} \rightarrow \text{it}$	(0.5) $V_8 \rightarrow sees$
(0.7) NP _S \rightarrow PRO _S	(0.3) D \rightarrow a	(0.5) $V_S \rightarrow$ cleans
$(0.3) \text{ NP}_{\text{S}} \rightarrow \text{D} \text{ N}_{\text{S}}$	(0.7) D \rightarrow the	$(0.5) V_{\rm P} \rightarrow \text{see}$
$(0.7) \operatorname{NP}_{\operatorname{P}} \operatorname{PRO}_{\operatorname{P}}$	$(0.1) N_{S} \rightarrow A N_{S}$	(0.5) $V_P \rightarrow \text{see}$ (0.5) $V_P \rightarrow \text{clean}$
$(0.3) \operatorname{NP}_{\mathrm{P}} \mathrm{D} \operatorname{N}_{\mathrm{P}}$	(0.1) N _P \rightarrow A N _P	(0.5) \vee_{P} > crean (1.0) A \rightarrow happy
		(1.0) A \checkmark happy

Example sentences

The boys clean the house

She cleans it

He sees the dog

The happy dogs see a tiger

 $(0.5) S \rightarrow NP_{S} VP_{S}$ $(0.5) S \rightarrow NP_{P} VP_{P}$ $(1.0) VP_{S} \rightarrow V_{S} NP_{S}$ $(1.0) VP_{P} \rightarrow V_{P} NP_{P}$ $(0.7) NP_{S} \rightarrow PRO_{S}$ $(0.3) NP_{S} \rightarrow D N_{S}$ $(0.7) NP_{P} \rightarrow PRO_{P}$ $(0.3) NP_{P} \rightarrow D N_{P}$

(0.3) $PRO_S \rightarrow he$ (0.3) $PRO_S \rightarrow she$ (0.4) $PRO_S \rightarrow it$ (0.3) $PRO_P \rightarrow her$ (0.3) $PRO_P \rightarrow him$ (0.3) $PRO_P \rightarrow him$ (0.4) $PRO_P \rightarrow it$ (0.3) $D \rightarrow a$ (0.7) $D \rightarrow the$ (0.7) $D \rightarrow the$ (0.1) $N_S \rightarrow A N_S$ (0.1) $N_P \rightarrow A N_P$

- (0.3) $N_S \rightarrow boy$
- (0.3) $N_S \rightarrow tiger$
- (0.3) $N_S \rightarrow dog$
- (0.2) $N_P \rightarrow boy$
- (0.2) $N_P \rightarrow tiger$
- (0.2) $N_P \rightarrow dog$
- (0.15) N_P \rightarrow school
- (0.15) N_P \rightarrow house
- (0.5) $V_S \rightarrow sees$
- (0.5) $V_S \rightarrow$ cleans
- (0.5) $V_{\rm P} \rightarrow \text{see}$
- (0.5) $V_P \rightarrow$ clean
- (1.0) $A \rightarrow happy$

Example sentences

The boys clean the house	She cleans it	The boys see	
She cleans He sees the dog	The happy dogs see a tig	er	
It is relatively easy to expand on this and (0.3) N _s \rightarrow boy			
$(0.5) S \rightarrow NP_{P} VP_{P}$ $(0.5) VP_{S} \rightarrow V_{S} NP_{S}$ $(0.5) VP_{S} \rightarrow V_{S}$ $(0.5) VP_{P} \rightarrow V_{P} NP_{P}$	(0.3) $PRO_S \rightarrow he$ (0.3) $PRO_S \rightarrow she$ (0.4) $PRO_S \rightarrow it$ (0.3) $PRO_P \rightarrow her$ (0.3) $PRO_P \rightarrow her$ (0.3) $PRO_P \rightarrow him$ (0.4) $PRO_P \rightarrow it$	(0.3) $N_S \rightarrow tiger$ (0.3) $N_S \rightarrow dog$ (0.2) $N_P \rightarrow boy$ (0.2) $N_P \rightarrow tiger$ (0.2) $N_P \rightarrow tiger$ (0.2) $N_P \rightarrow dog$ (0.15) $N_P \rightarrow school$ (0.15) $N_P \rightarrow house$	
$(0.7) \text{ NP}_{S} \rightarrow \text{PRO}_{S}$ $(0.3) \text{ NP}_{S} \rightarrow \text{D N}_{S}$ $(0.7) \text{ NP}_{P} \rightarrow \text{PRO}_{P}$	$(0.3) D \rightarrow a$ $(0.7) D \rightarrow the$ $(0.1) N_{S} \rightarrow A N_{S}$ $(0.1) N_{P} \rightarrow A N_{P}$	(0.5) $V_S \rightarrow sees$ (0.5) $V_S \rightarrow cleans$ (0.5) $V_P \rightarrow see$ (0.5) $V_P \rightarrow clean$ (1.0) $A \rightarrow happy$	

Example sentences

The boys behind the school clean the house.

He sees the dog with it

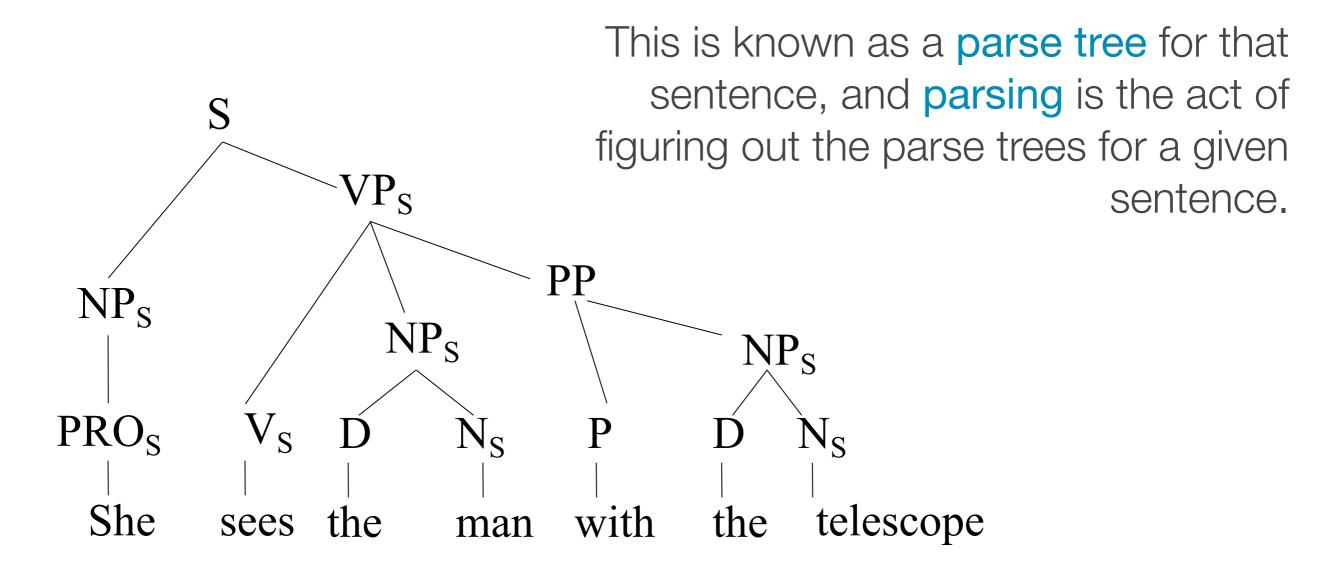
She sees the dog behind a tiger

(0.5) S \rightarrow NP_S VP_S (0.5) S \rightarrow NP_P VP_P (0.4) VP_S \rightarrow V_S NP_S (0.2) VP_S \rightarrow V_S NP_S PP (0.4) VP_S \rightarrow V_S (0.4) VP_P \rightarrow V_P NP_P (0.2) VP_P \rightarrow V_P NP_P PP (0.4) VP_p \rightarrow V_p (0.6) NP_S \rightarrow PRO_S (0.3) NP_S \rightarrow D N_S (0.6) NP_p \rightarrow PRO_p (0.3) NP_p \rightarrow D N_p (0.1) NP_S \rightarrow NP_S PP (0.1) NP_p \rightarrow NP_p PP

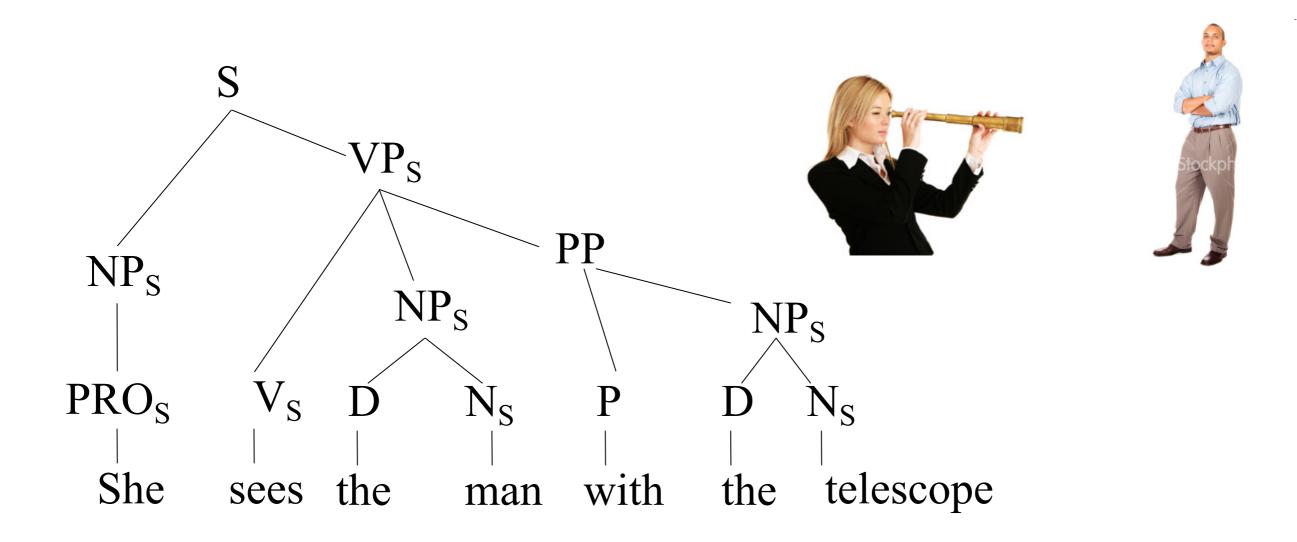
(0.5) PP \rightarrow P NP_s (0.5) PP \rightarrow P NP_P (0.3) PRO_S \rightarrow he (0.3) $PRO_S \rightarrow she$ (0.4) $PRO_s \rightarrow it$ (0.3) PRO_P \rightarrow her (0.3) PRO_P \rightarrow him (0.4) PRO_p \rightarrow it (0.3) D \rightarrow a (0.7) D \rightarrow the (0.1) N_S \rightarrow A N_S (0.1) N_p \rightarrow A N_p (0.5) P \rightarrow with (0.5) P \rightarrow behind

- (0.3) $N_S \rightarrow boy$
- (0.3) $N_S \rightarrow tiger$
- (0.3) $N_S \rightarrow dog$
- (0.2) $N_P \rightarrow boy$
- (0.2) $N_P \rightarrow tiger$
- (0.2) $N_P \rightarrow dog$
- (0.15) N_P \rightarrow school
- (0.15) N_P \rightarrow house
- (0.5) $V_s \rightarrow sees$
- (0.5) $V_s \rightarrow$ cleans
- (0.5) $V_P \rightarrow see$
- (0.5) $V_P \rightarrow$ clean
- (1.0) $A \rightarrow happy$

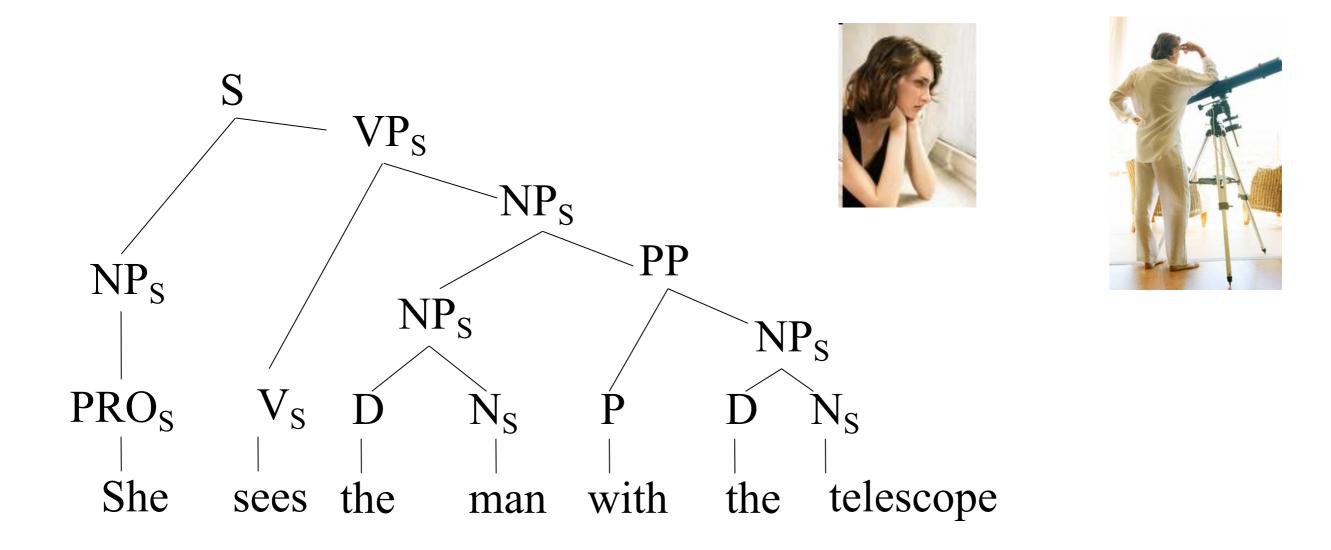
Yield sentences with hierarchical phrase structure, in which phrases can be nestled hierarchically within one another.



Many sentences are ambiguous - they have multiple possible parse trees



Many sentences are ambiguous - they have multiple possible parse trees



This can often be a source of unintentional humour

Don't let worry kill you - let the church help. Ingres enjoyed painting his models nude. Visiting relatives can be boring.

Iraqi head seeks arms

Grandmother of eight makes hole in one

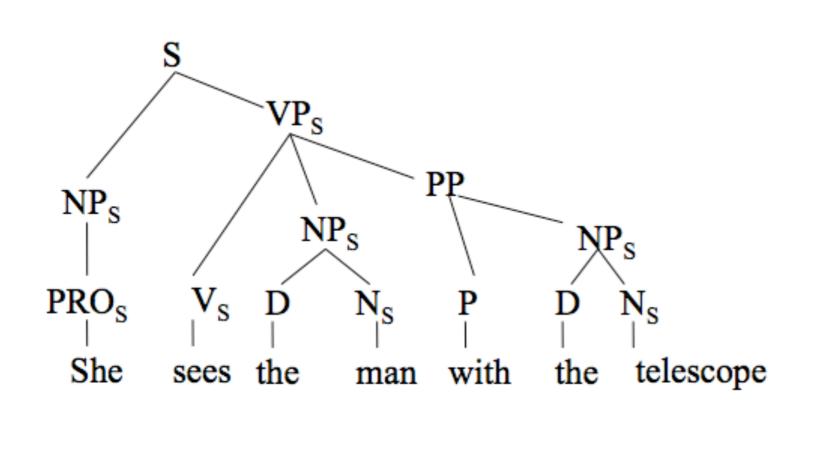
Two sisters reunite after eighteen years at checkout counter

Dr. Ruth to talk about sex with newspaper editors

These sorts of misunderstandings are one of the pieces of evidence suggesting that the underlying parse trees are psychologically "real"

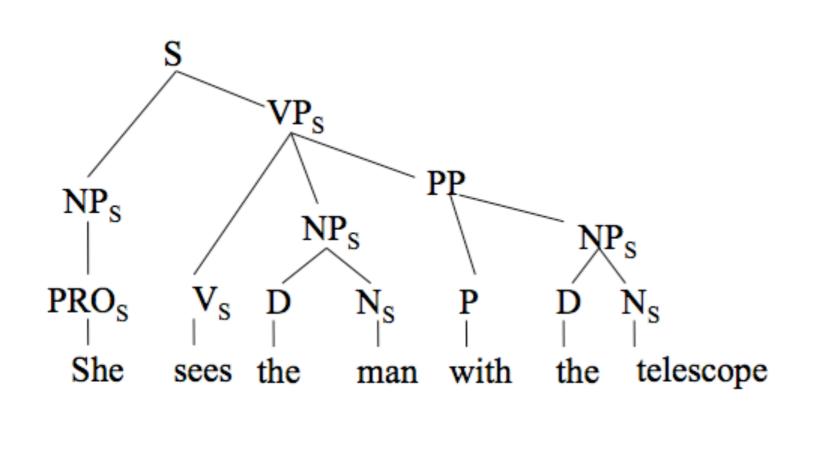
The probability of a parse is the probability of each of the rules used to generate that parse

0.5*0.6*0.3*0.2*0.5*0.3*0.7*0.3*0.5*0.5*0.3*0.7*0.2 = 5.95e-6



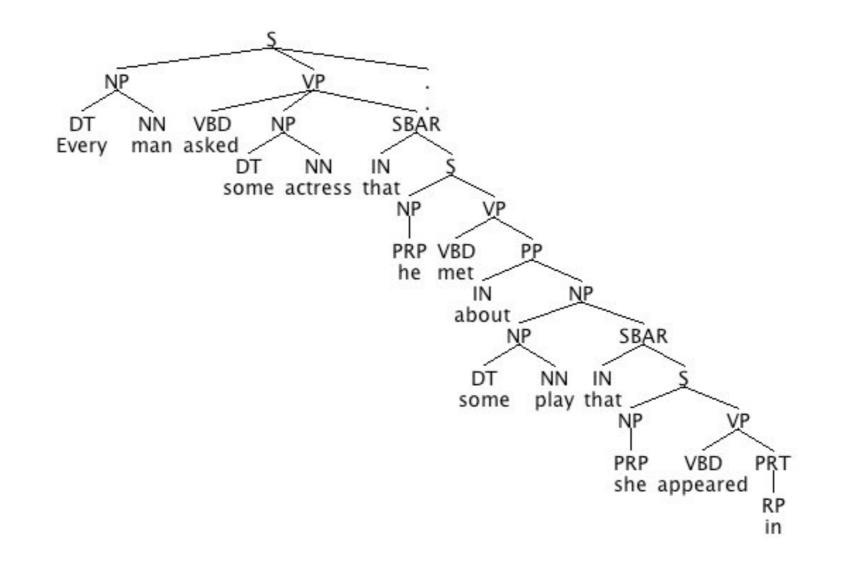
(0.5) S → NP_S VP_S (0.6) NP_S → PRO_S (0.3) PRO_S → she (0.2) VP_S → V_S NP_S PP (0.5) V_S → sees (0.3) NP_S → D N_S (0.7) D → the (0.3) N_S → man (0.5) PP → P NP_S (0.5) P → with (0.7) D → the (0.2) N_S → telescope If the sentence is ambiguous, you need to add the probabilities of each of the possible parses

0.5*0.6*0.3*0.2*0.5*0.3*0.7*0.3*0.5*0.5*0.3*0.7*0.2 + 0.5*0.6*0.3*0.4*0.5*0.3*0.3*0.7*0.3*0.5*0.5*0.3*0.7*0.2 = 9.52e-6

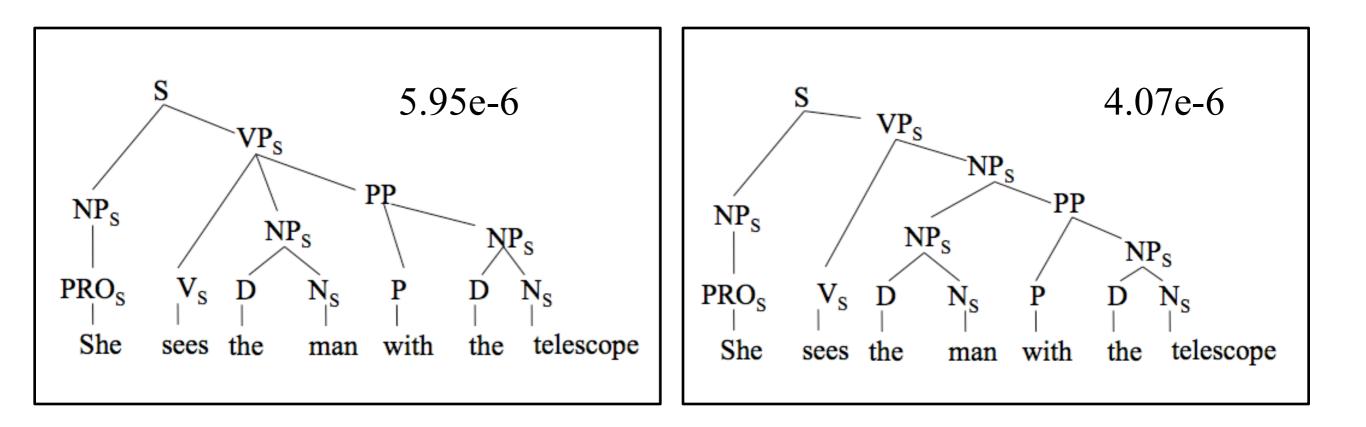


(0.5) S → NP_S VP_S (0.6) NP_S → PRO_S (0.3) PRO_S → she (0.2) VP_S → V_S NP_S PP (0.5) V_S → sees (0.3) NP_S → D N_S (0.7) D → the (0.3) N_S → man (0.5) PP → P NP_S (0.5) P → with (0.7) D → the (0.2) N_S → telescope More massive grammar = more ambiguous sentences.

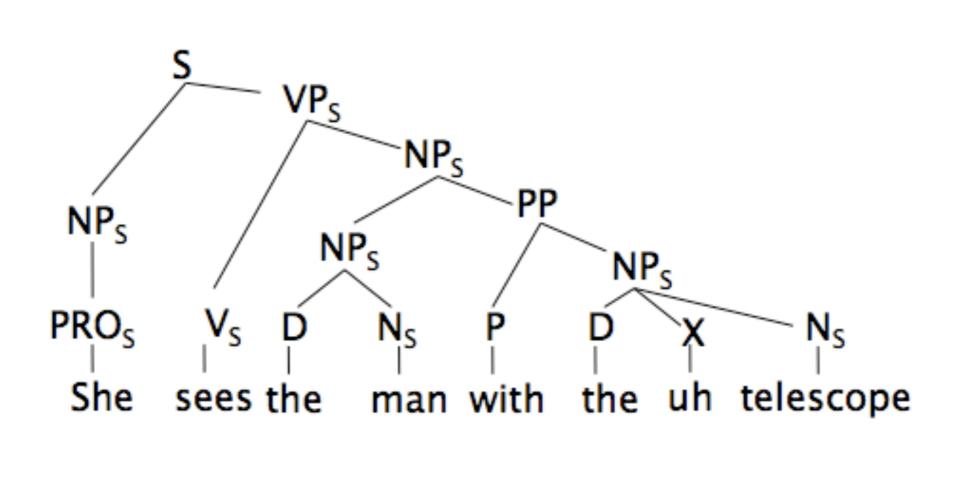
Grammars that are typically used in computational linguistics have many ambiguous parses.



A PCFG gives some idea of the plausibility of different parses; however, this is often not very linguistically accurate, since it doesn't take into account **semantics** (meaning) or local lexical context



Real language contains a lot of grammatical mistakes; PCFGs can be fairly robust to those, at the price of having many incorrect (but very low-probability) rules.



(0.5) S \rightarrow NP_S VP_S (0.6) NP_S \rightarrow PRO_S (0.3) $PRO_S \rightarrow she$ (0.4) VP_S \rightarrow V_S NP_S (0.5) V_S \rightarrow sees (0.29) NP_S \rightarrow D N_S (0.01) NP_S \rightarrow D X N_S (0.7) D \rightarrow the (0.3) N_S \rightarrow man $(0.5) PP \rightarrow P NP_{S}$ (0.5) P \rightarrow with (0.7) D \rightarrow the (0.2) N_S \rightarrow telescope $(1.0) X \rightarrow uh$

CFGs are useful because:

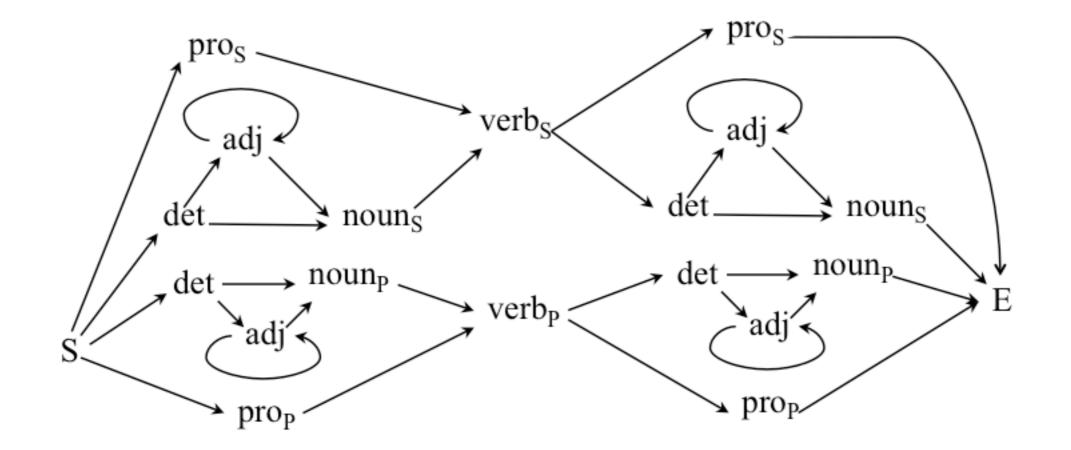
They are tractable, and more realistic models of language than HMMs or n-grams

But we still use HMMs and n-grams because:

They are much *more* tractable, and scale better with large vocabularies.

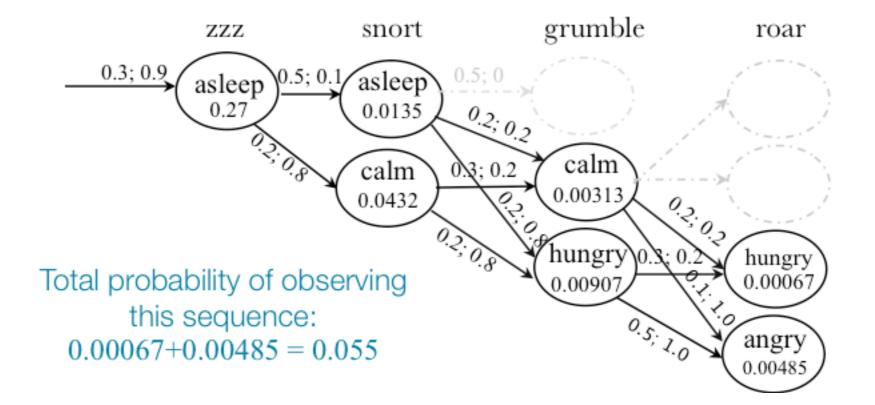
In practice, most state-of-the-art stuff combines these different techniques to try to take advantage of the best aspects of each





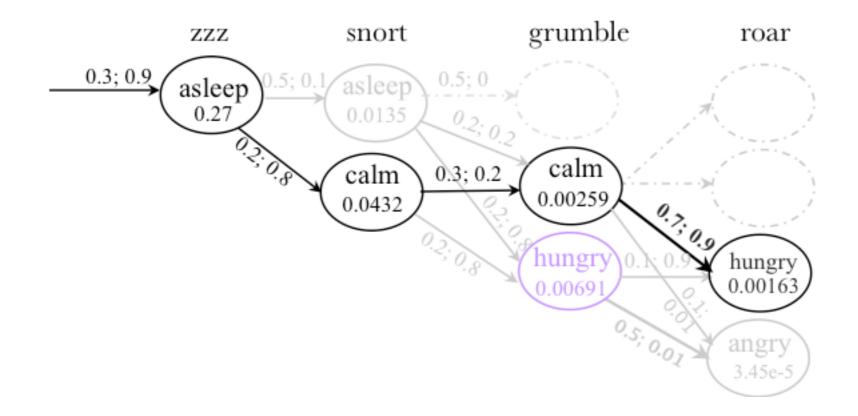


Forward algorithm: calculate the probability of an observation





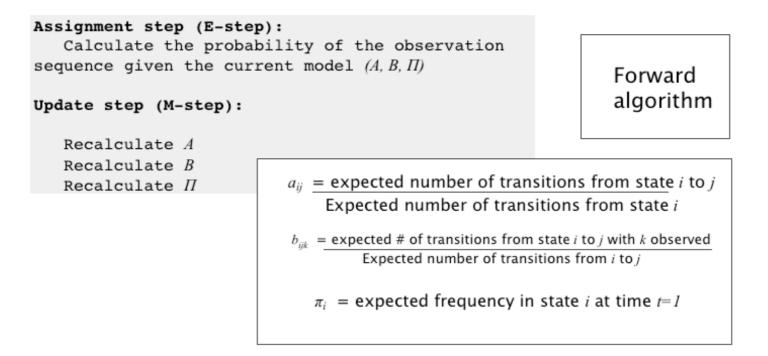
- Forward algorithm: calculate the probability of an observation
- Viterbi algorithm: calculate the most likely path through an HMM





- Forward algorithm: calculate the probability of an observation
- Viterbi algorithm: calculate the most likely path through an HMM

Baum-Welch algorithm: figure out the most likely model given a set of observations

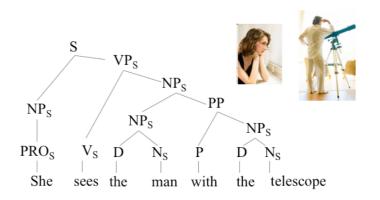




- Forward algorithm: calculate the probability of an observation
- Viterbi algorithm: calculate the most likely path through an HMM

Baum-Welch algorithm: figure out the most likely model given a set of observations

Context free grammars: Are a much better model for language because they have hierarchical phrase structure





- Forward algorithm: calculate the probability of an observation
- Viterbi algorithm: calculate the most likely path through an HMM
- Baum-Welch algorithm: figure out the most likely model given a set of observations
- Context free grammars: Are a much better model for language because they have hierarchical phrase structure

Starting next time: switching gears again to how people use data. In particular, we'll talk about how the informativeness of data depends on how it was sampled and the structure of the hypotheses (and whether people are aware of this)

Additional references (not required)

HMMs

- ▶ Wikipedia entry on CFGs is also pretty good!
- Manning, C., & Schutze, H. (1999). Foundations of statistical natural language processing. Chapter 11.
- ▶ Russell, S., & Norvig, P. (1995). Artificial Intelligence: A modern approach. (This one is first edition, but all editions have good resources on grammars). Chapter 22